



WEBINAR SERIES ON ADVANCED MOBILITY

Acknowledgement

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Distributed Joint Radar-Communications



Kumar Vijay Mishra

United States DEVCOM Army Research Laboratory



IEEE Vehicular Technology Society

Webinar Series on Advanced Air Mobility

13 November 2023

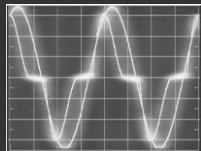
About the speaker

Kumar Vijay Mishra

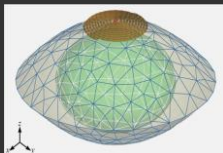
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- ARL Senior Fellow, United States DEVCOM Army Research Laboratory
- Research Fellow, SnT, U of Luxembourg
- Technical Advisor: Hertzwell, Singapore; Aura Intelligent Systems, Boston
- Vice-Chair, URSI Commission C
- Editor, IEEE Transactions on Aerospace and Electronic Systems
- Vice-Chair, IEEE Synthetic Aperture Standards Committee; Member, IEEE SPS SAM, SPS TWG on Synthetic Apertures, INGR IEEE International Network Generations Roadmap, AESS Radar Systems Panel
- Founding member, IEEE ComSoc ISAC ETI
- Research Interests:

Radar



Signal Processing



Electromagnetics



Communications



Remote Sensing



Courtesy: For All Mankind (S02E01)



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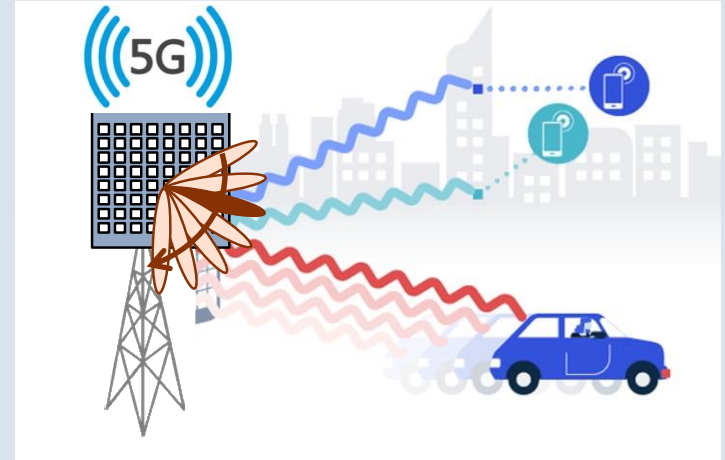
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Courtesy: The Tomorrow War (2021)

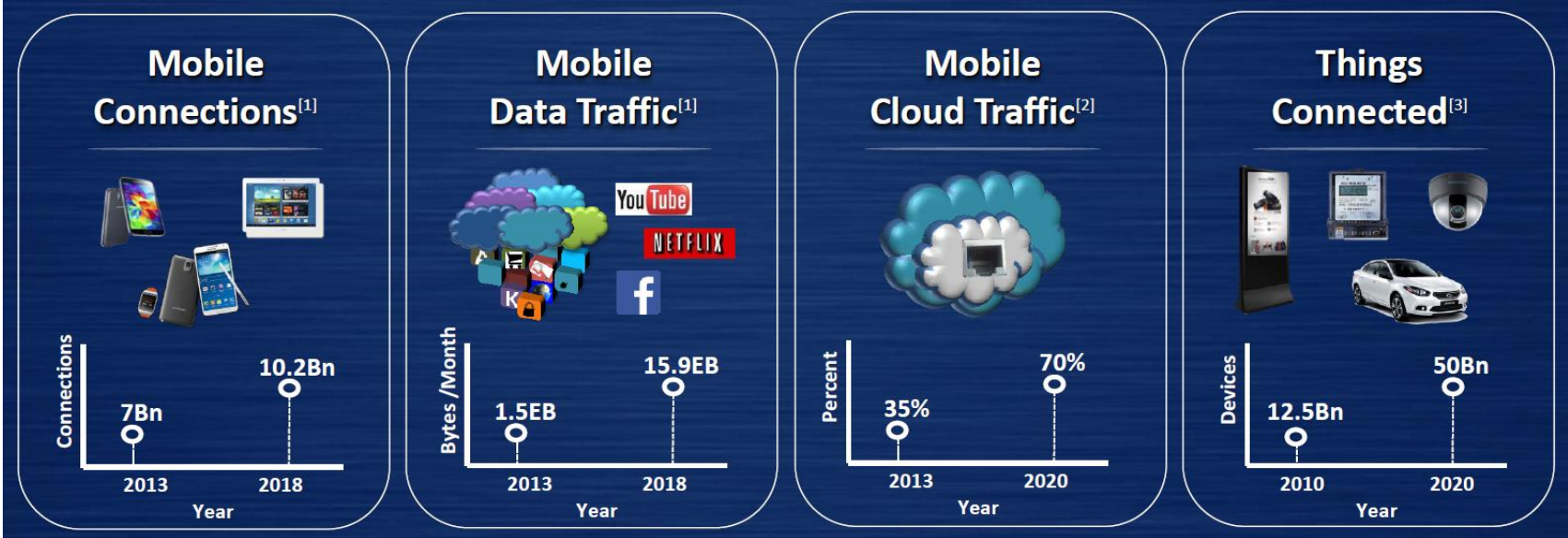


*I found my passion
in the Army Research Lab.*

Motivation



Wireless Communications Trends



- Increasing number of connected devices
- Increasing demand in high quality wireless services

[1] VNI Global Mobile Data Traffic Forecast 2013-2018, Cisco, 2014

[2] The Mobile Economy, GSMA, 2014

[3] Internet of Things, Cisco, 2013

EB (Exa Bytes) = 1,000,000 TB (Tera Bytes)

Bn= Billions

How to Meet Demand in Current Landscape?

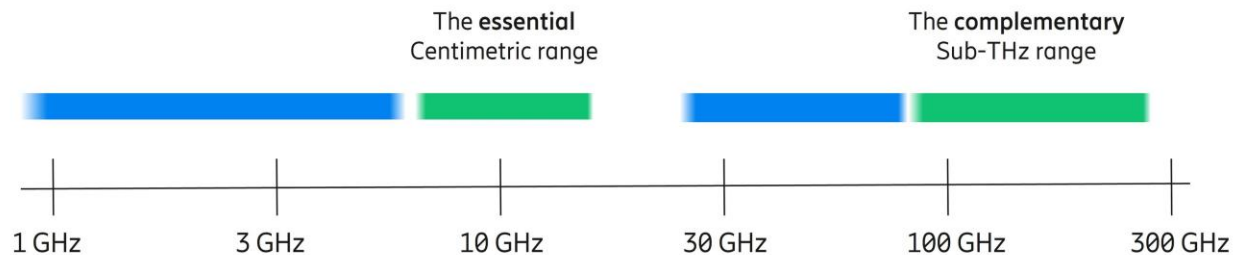
Measure for Throughput : Shannon formula as a guide

$$C = n W \log(1 + \text{SINR})$$

Bandwidth W

- Higher the better → Linear dependence
- Depends on spectrum allocation
- Natural resource, scarce
- Not everything is useful, expensive
- Maximize the spectral efficiency bits/sec/ Hz

Spectrum range for future radio access



Current 5G spectrum range

Possible new 6G spectrum range

Reference: Ericsson, 2022

1986

The New York Times

PLAN TO REALLOCATE PART OF RADIO BAND DISPUTED

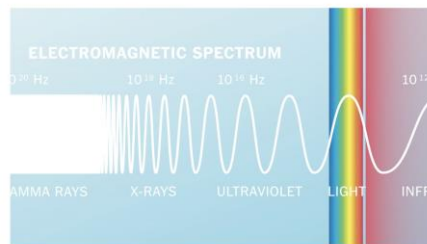
By Reginald Stuart, Special To the New York Times
July 6, 1986

2012

The New York Times

Carriers Warn of Crisis in Mobile Spectrum

Give this article



Wireless companies say that smartphones are threatening to overwhelm their networks, and are asking the government for help. But some experts maintain that technology already has the answers.

By Brian X. Chen
April 17, 2012

AT&T, Verizon, T-Mobile and Sprint say they need more radio spectrum, the government-rationed slices of radio waves that carry phone calls and wireless data.

2021

Bloomberg Wealth

Sign in

Photographer: Angel G

Billionaires Musk, Ergen and Dell Brawling Over Spectrum at FCC

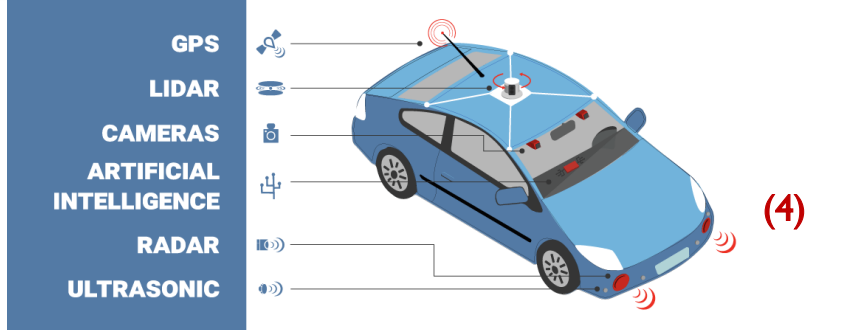
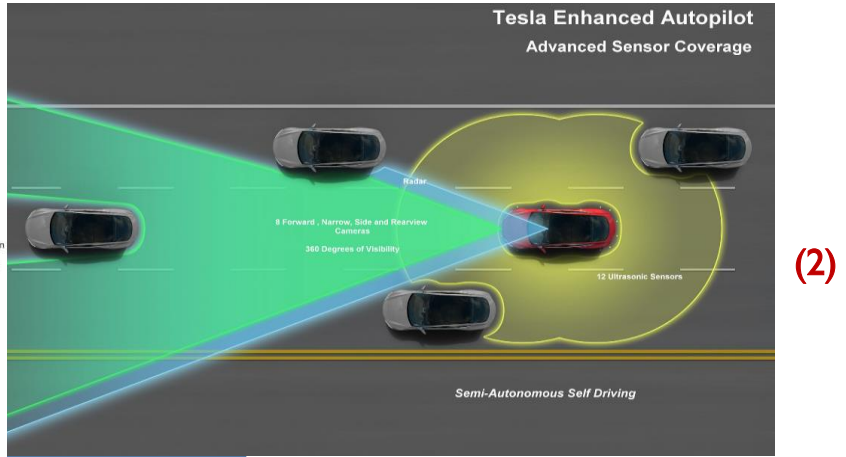
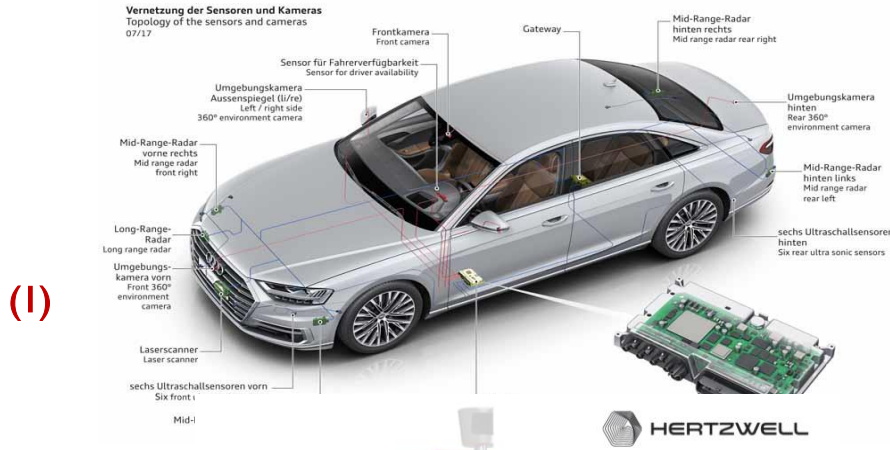
By Todd Shields + Follow
October 9, 2021, 8:45 AM EDT

- ▶ Fight boils over for spectrum needed for proposed 5G service
- ▶ Disagreement on whether service would foul SpaceX signals

Live on Bloomberg
Watch Live TV
Listen to Live Radio

Bloomberg
Television

Sensor-Driven Vehicles






©. Audi, <https://www.autonomousvehicletech.com/articles/136-the-new-audi-a8-reaches-level-3>

© 2. Qualcomm, Tesla, Audi, <https://www.texas.aaa.com/automotive/advocacy/self-driving-cars-autonomous-vehicles-explained.html>

© 3. Hertzwell

© 4. Owners, graphic from web

Automotive Sensors

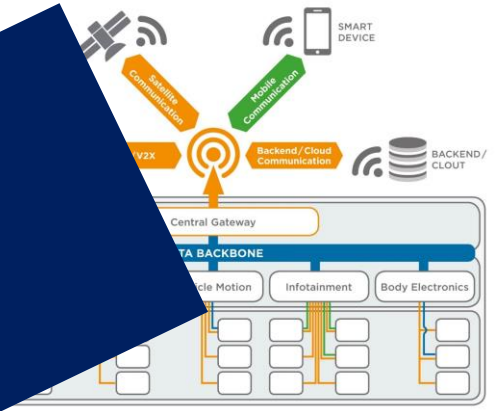
Parameter	RADAR 	LIDAR 	Camera 
Nature	Active	Active	Passive
Range	Long Upto 250m	Mid-range Upto 100m	Near range Upto 15-20m
Accuracy	<ul style="list-style-type: none"> • Descent • 0.1 m, • ± 0.1 m/s • H/V-FOV 30/50 	<ul style="list-style-type: none"> • Good • 0.02 m • 0.1deg • 360deg H-FOV 	<ul style="list-style-type: none"> • Good • Recognition at 15m
Observations	<ul style="list-style-type: none"> • Robust to harsh conditions • Detecting Doppler • Low cost • Lack of semantic information 	<ul style="list-style-type: none"> • High Accuracy • 3D Mapping • High cost 	<ul style="list-style-type: none"> • Semantic information • Poor performance in adverse weather, night • No Doppler information

In Addition, Modern Cars are ...

Software-Managed

Connected Car & Device Platform Volkswagen Group	Intelligent Body & Cockpit Audi	Automated Driving Audi	Vehicle Motion & Energy Porsche	Digital Business & Mobility Services Volkswagen Passenger Cars
Transform multiple Backends into One Volkswagen Automotive Cloud	Development of a cross-brand, standardized cockpit and body platform for all future E/E-architectures – the "One Infotainment Platform"	A One SW-Stack, cross-branded approach for Autonomous Driving/Parking and Driver Assistance Systems, scalable from NCAP to Level 3 and beyond	Development and delivery of powertrain, chassis and energy/charging software functions, located in high performance computing centers	Definition of experience

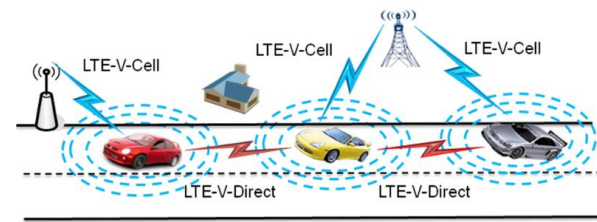
... and Connected!



Autonomous Vehicles need high BW
 1) To sense accurately
 2) To stay connected
 Q: Where is the BW?

Performance	Example Applications
24Gbps	Uncompressed ADAS (Level 3-4 Autonomous)
12Gbps	Advanced Infotainment Sensor Data (e.g. 4K video)
3Gbps	Infotainment (e.g. full HD video)
1Gbps	Legacy Entertainment Systems Dashboard/ Touch Screens
150Mbps	In-vehicle Networks (e.g. Apps, Traffic, Vehicle Health Report)

Access technologies
 DSRC
 C-V2X



© VW-Software-Anwendungsgebiete. Quelle: VW,
 © IEEE, <https://spectrum.ieee.org/transportation/advanced-cars/6-key-connectivity-requirements-of-autonomous-driving>
 © IEEE Spectrum, Data from Cisco blog, VTS Society

IEEE Spectrum Allocation

Modern radar/comms operate in an increasingly crowded RF spectrum

Radars need to use full bandwidth and undertake continuous transmissions

IEEE Radar band	VHF/UHF [30 MHz – 1 GHz]	L [1-2 GHz]	S [2-4 GHz]	C [4-8 GHz]	X [8-12 GHz]	Ku, K, Ka, V, W [12-300 GHz]
Examples of radar usage	FOPEN	ARSR	ASR, NEXRAD	TDWR	CASA	Automotive radars, cloud radars
Co-existing comms	TV/broadcast/ 802.11ah/f	WiMAX, JTIDS	LTE	802.11a/ac	LTE	802.11ad, mmwave comm

AVIATION TODAY 2022

US Airlines Begin Installing 5G C-Band Filter for Radio Altimeters on Airbus A320s

By Woodrow Bellamy III | September 14, 2022
Send Feedback | @WBellamyIIIAC

5G C-Band, Airbus A320, airlines, FAA, radio altimeter, U.S.

f t e in b



THE CONVERSATION

Academic rigor, journalistic flair
Radio interference from satellites is threatening astronomy – a proposed zone for testing new technologies could head off the problem
Authors

2023

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Shared Spectrum Access for Radar and Communications (SPARC)

2nd EARS Workshop
Welcome to the 2nd Workshop on ENHANCING ACCESS TO THE RADIO SPECTRUM
OCTOBER 19 - 20, 2015
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Platforms for Advanced Wireless Research

SPECTRUM X
An NSF Spectrum Innovation Center



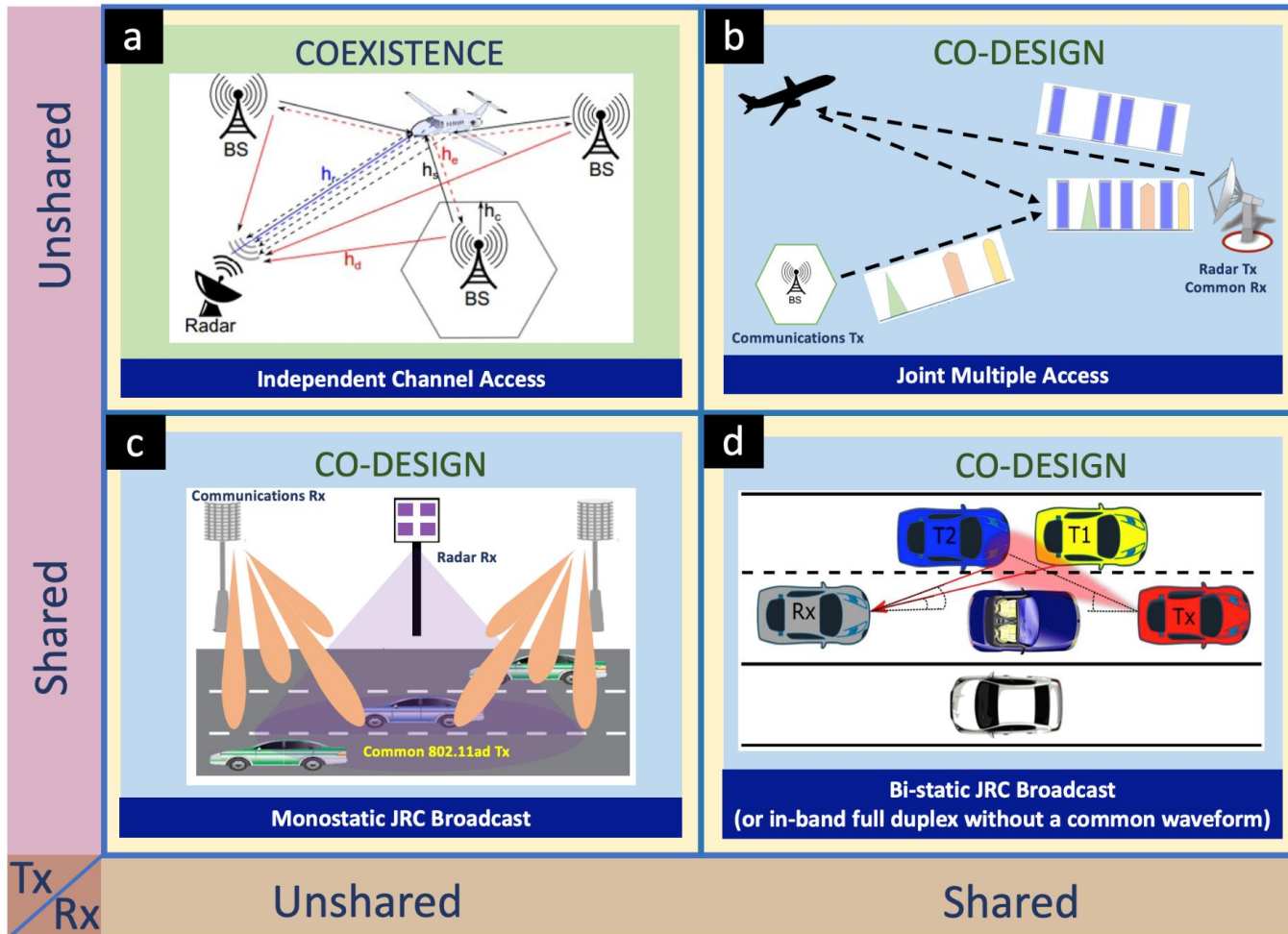
Spectrum and Wireless Innovation enabled by Future Technologies (SWIFT)

LINCOLN LABORATORY MASSACHUSETTS INSTITUTE OF TECHNOLOGY

2016 THE THREAT TO WEATHER RADARS BY WIRELESS TECHNOLOGY



Integrated Sensing and Communications (ISAC) Topologies



More ISAC Topologies

Channel Access	Hardware	Waveform
<ul style="list-style-type: none">◆ Independent◆ Coordinated◆ Joint◆ Shared	<ul style="list-style-type: none">◆ Separate Tx & Rx◆ Same Tx, Common Rx◆ Common Tx, Same Rx◆ Common Tx & Rx	<ul style="list-style-type: none">◆ Separate◆ Common◆ Resource-shared
Location	Performance/Functionality	Specialized
<ul style="list-style-type: none">◆ Colocated◆ Bi-static◆ Distributed◆ Networked◆ Heterogeneous	<ul style="list-style-type: none">◆ Radar-centric◆ Comms-centric◆ Joint radar-comms◆ Dual-Function Radar-Comms	<ul style="list-style-type: none">◆ MRMC◆ IBFD ISAC◆ IRS-Aided ISAC◆ mmWave, THz, VLC, quantum

Outline

```
graph TD; Node1(( )) --- Box1[Motivation & Challenges]; Node2(( )) --- Box2[Automotive JRC, Full-Duplex ISAC, Learning]; Node3(( )) --- Box3[Wi-Fi Protocol for Radar, Weather Sensing]; Node4(( )) --- Box4[Dual-Blind Deconvolution];
```

Motivation & Challenges

Spectral Co-Design

Automotive JRC, Full-Duplex ISAC, Learning

Opportunistic ISAC

Wi-Fi Protocol for Radar, Weather Sensing

Spectral Co-Existence

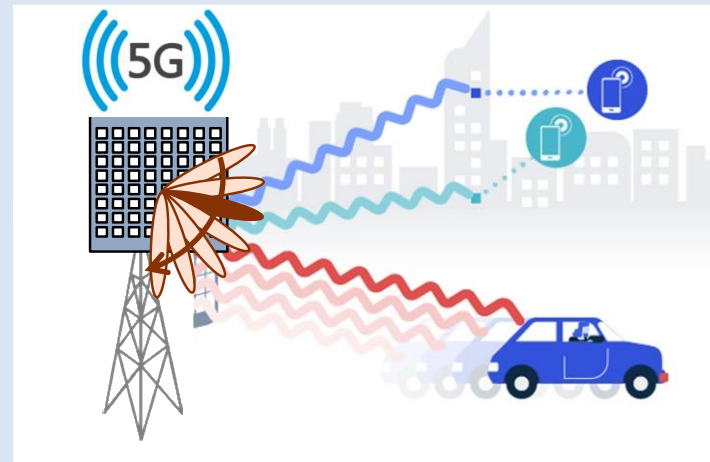
Dual-Blind Deconvolution

Courtesy: Citadel (S01E06)



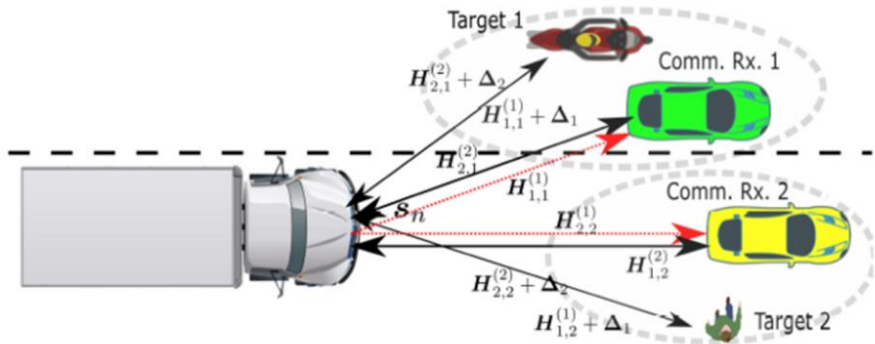
It'll be on the sail
by the antenna array.

Spectral Co-Design Automotive JRC

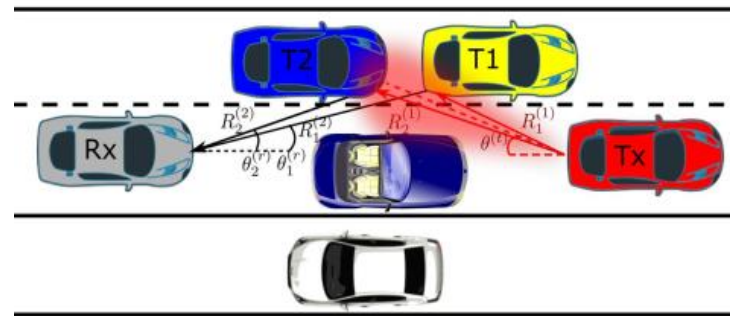


Monostatic and Bi-Static Systems

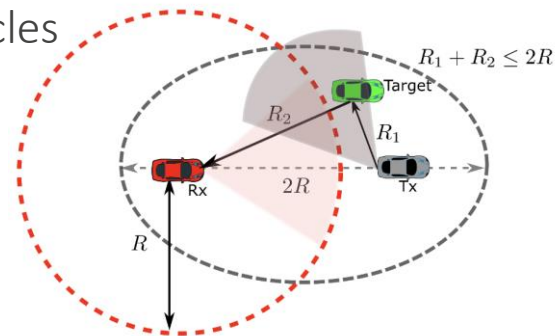
Monostatic



Bi-static

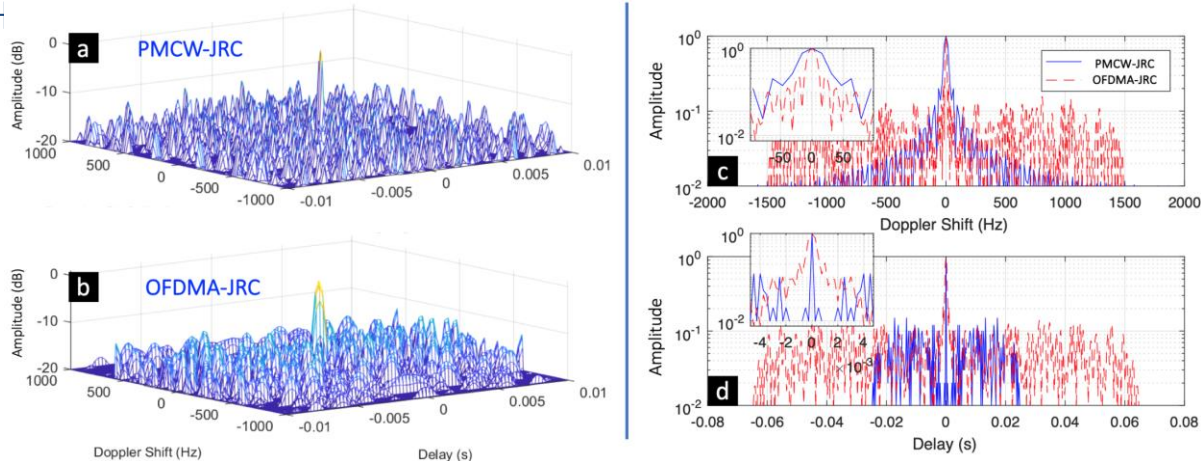


- Bi-static radar exploits bounced-off Tx signals from other vehicles
- Extends sensing area to NLOS w.r.t. Rx
- Communications is more susceptible to interference from surroundings than the direct path
- Bi-static system is more general

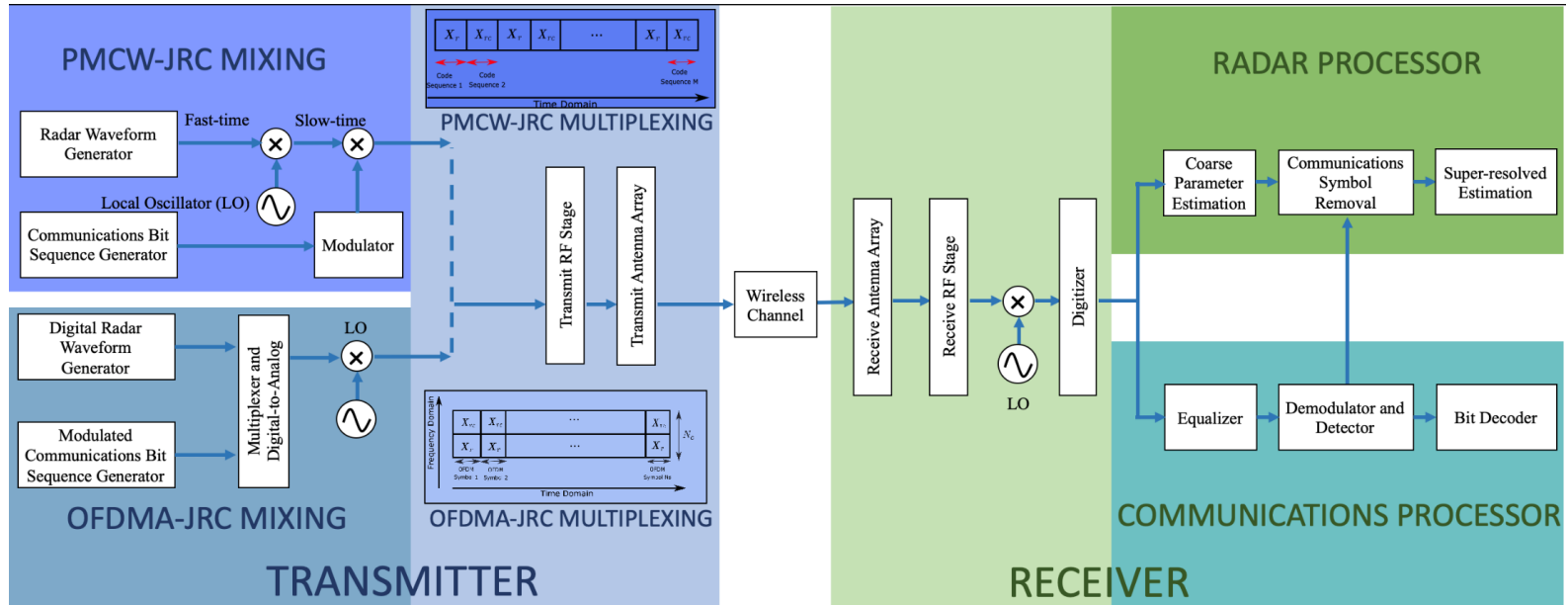


Two waveforms for mm-Wave JRC

- PMCW
 - Viable alternative to FMCW for high-res radars
 - No linear frequency ramp (and simpler on-chip implementations) for range estimation
 - Sharp, thumbtack ambiguity function; MIMO radar in code domain; embedded comms
- OFDMA
 - Differentiates users in both time and frequency (unlike OFDM in time-only)
 - Stable performance in multipath fading and relative simple synchronization
 - High dynamic range and efficient receiver processing based on FFT
- Question: H

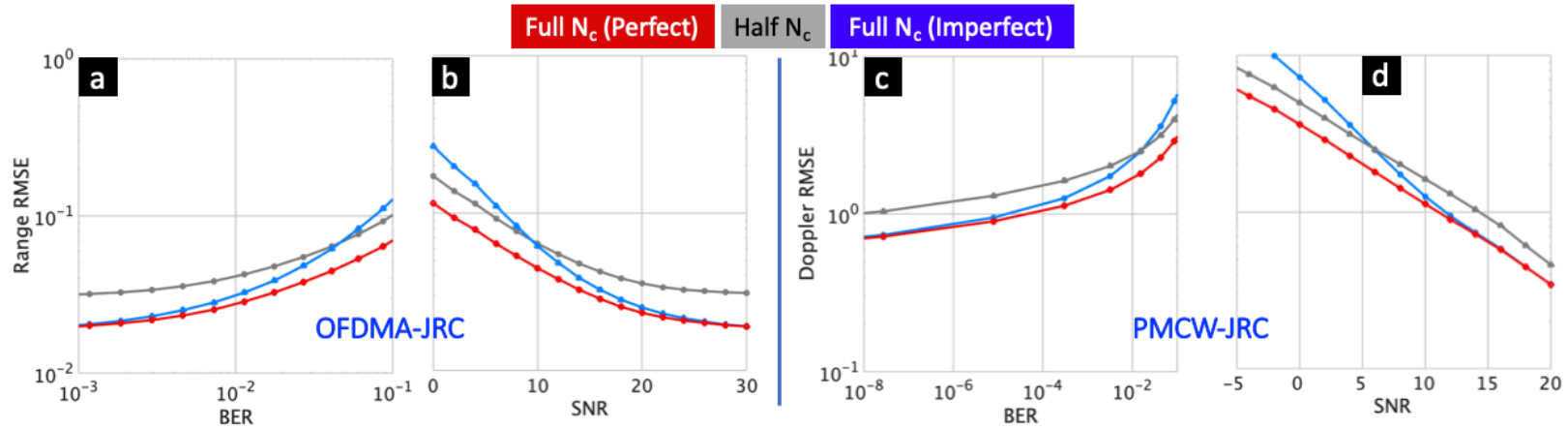


mm-Wave Tx-Rx Design



- Multiplexing strategy required to enhance waveform identifiability
- The receive processing consists of coarse and super-resolution steps
- JRC super-resolution algorithm has lower complexity than 2D-FFT and 2D-MUSIC

mm-Wave JRC Performance



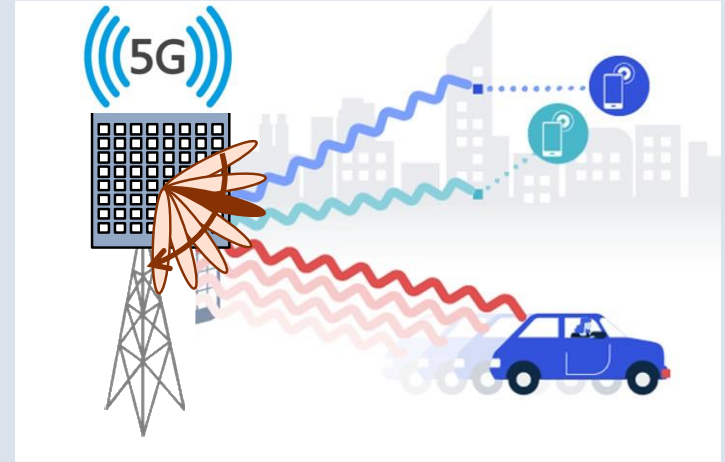
- A comparison of estimation errors in the coupled parameter - range for OFDMA-JRC and Doppler for PMCW-JRC
- When SNR is above a threshold, re-estimating coupled parameter using all subcarriers after comm removal enhances the recovery
- At low SNR, radar-only frames/carriers are a more optimal choice

Courtesy: Citadel (S01E06)

Duke will maintain altitude
at 5,000 feet to avoid radar.

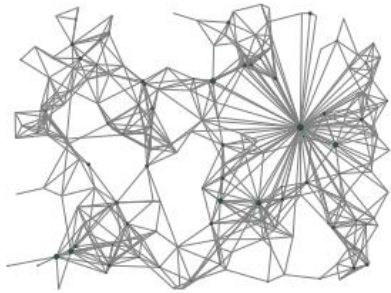
Spectral Co-Design

Distributed IBFD ISAC

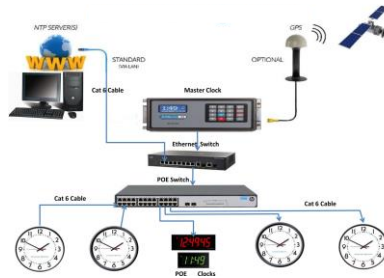


Distributed ISAC Considerations

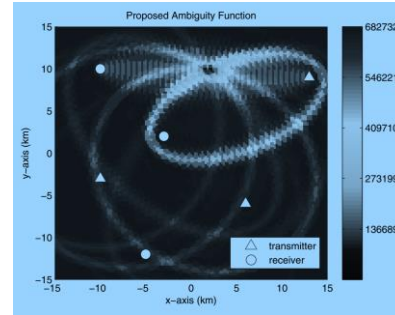
Challenge: Future networks will be more decentralized and edge-focused
Current research devoted to colocated/centralized ISAC



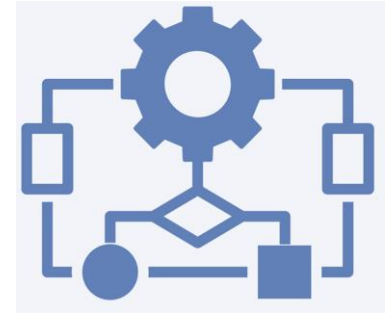
Complexity



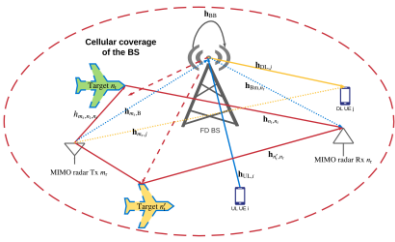
Synchronization



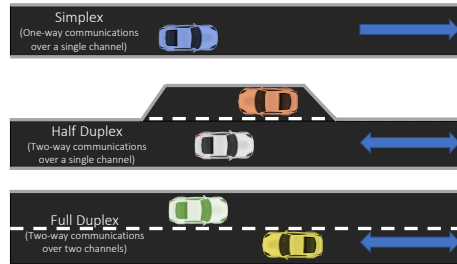
Statistical Design



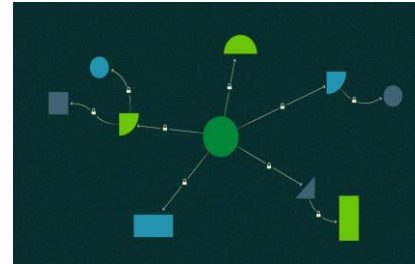
Speed



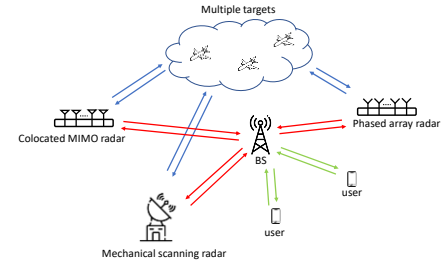
Data Association



Duplexing

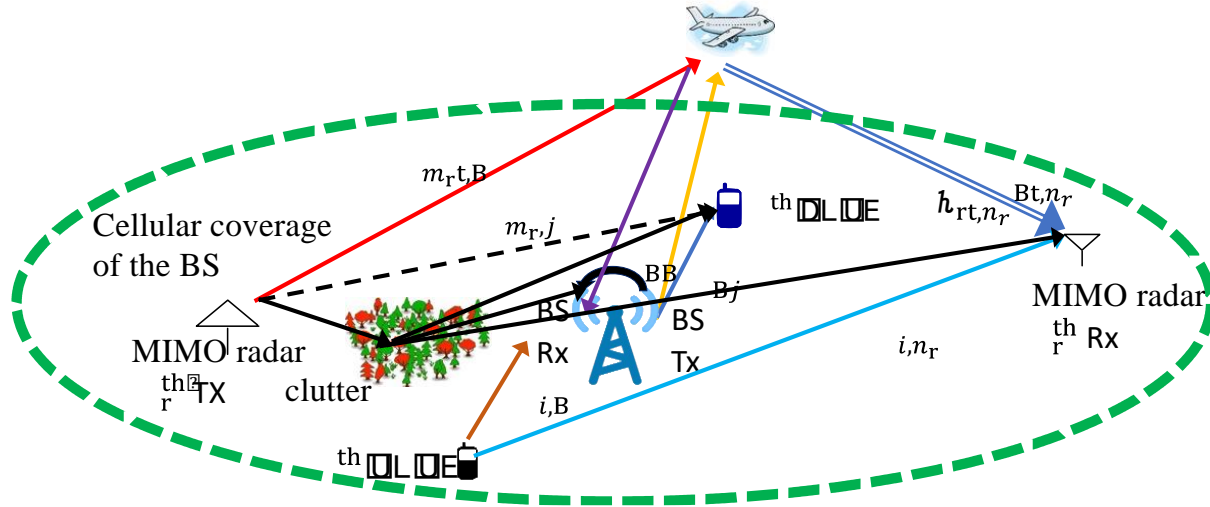


Fusion Center



Architectures

Statistical/Distributed Co-Design MRMC



Target RCS is not identical for all Tx-Rx pairs; modeled statistically

Radars work in cooperation with the downlink-reflected signal

IBFD MU-MIMO comms transmit while receiving target echoes

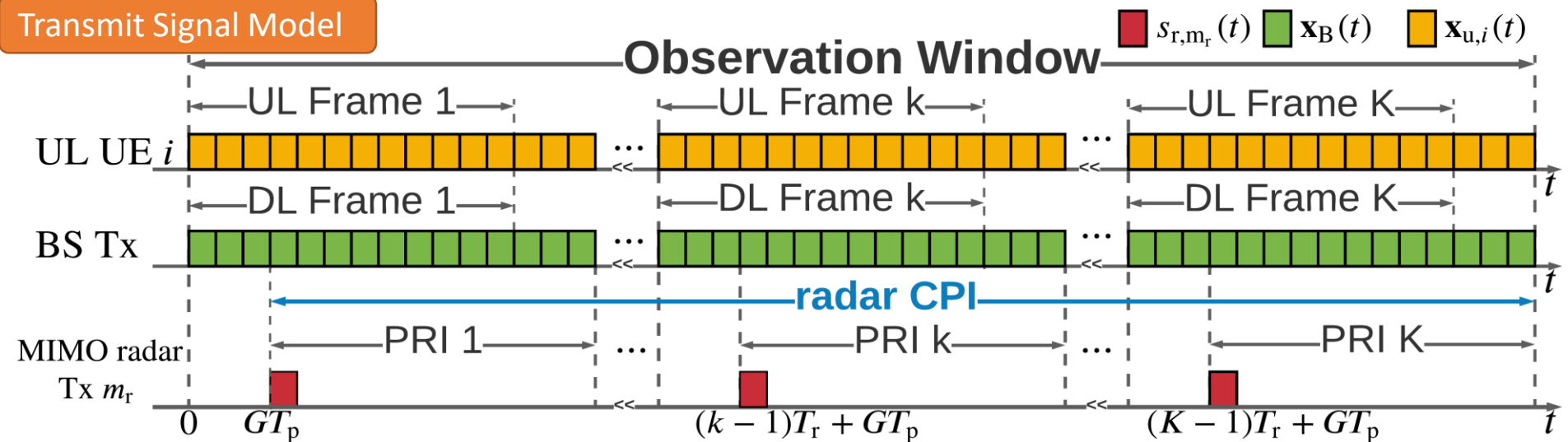
Determine a common metric for both radar and comms

Compounded and weighted sum mutual information as metric

Practical constraints: power budget, QoS, and PAR

Spectral Codesign System model

Transmit Signal Model



$$\text{UL UE } i: \mathbf{x}_{u,i}(t) = \sum_{k=0}^{K-1} \sum_{l=0}^{N-1} \mathbf{P}_{u,i}[k] \mathbf{d}_{u,i}[k, l] p_T(t - (kN + l)T_p)$$

Precoder of UL UE i

Data stream of UL UE i

Transmit pulse shape filter

$$\text{Radar Tx } m_r: s_{m_r}(t) = \sum_{k=0}^{K-1} \underbrace{a_{m_r,k}}_{\text{Radar Tx } m_r \text{ code in the } k\text{-th PRI}} \phi_{m_r}(t - kT_r - GT_p)$$

Radar Tx m_r code in the k -th PRI

$$\text{BS Tx: } \mathbf{x}_B(t) = \sum_{j=1}^J \sum_{k=0}^{K-1} \sum_{l=0}^{N-1} \mathbf{P}_{d,j}[k] \mathbf{d}_{d,j}[k, l] p_T(t - (kN + l)T_p)$$

Precoder of DL UE j

Data stream for DL UE j

Spectral Codesign System model

Composite Receive Signal Model

Receive Signal at BS Rx to decode UL UE i:

$$\mathbf{y}_i^u[k, l] = \mathbf{y}_{u,i}[k, l] + \mathbf{y}_{um,i}[k, l] + \mathbf{y}_{rB}[k, l] + \mathbf{y}_{BB}[k, l] + \mathbf{z}_B[k, l]$$

Multuser-interference

FD Self-interference

Receive Signal at DL UE j:

$$\mathbf{y}_j^d[k, l] = \mathbf{y}_{d,j}[k, l] + \mathbf{y}_{dm,j}[k, l] + \mathbf{y}_{u,j}[k, l] + \mathbf{y}_{r,j}[k, l] + \mathbf{z}_{d,j}[k, l]$$

UL interfering signal

Receive Signal at radar Rx n_r :

$$\mathbf{y}_{n_r}^r[k] = \mathbf{y}_{rt,n_r}[k] + \mathbf{y}_{Bt,n_r}[k] + \mathbf{y}_{Bm,n_r}[k] + \mathbf{y}_{u,n_r}[k] + \mathbf{y}_{c,n_r}[k] + \mathbf{z}_{r,nr}[k]$$

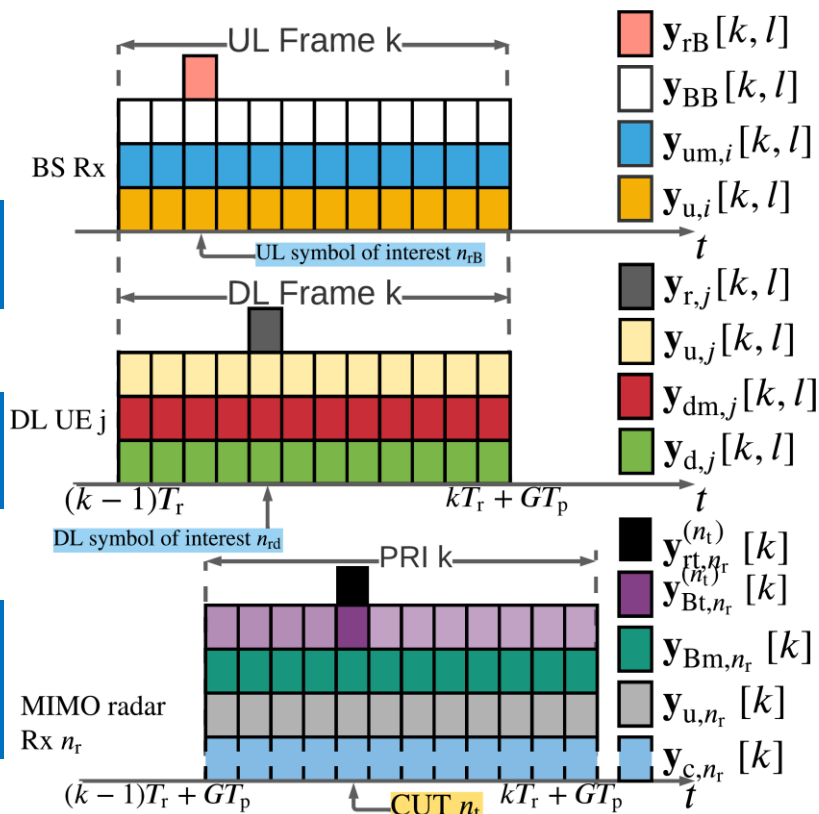
Target reflected DL signal

Multi-path propagated DL signal

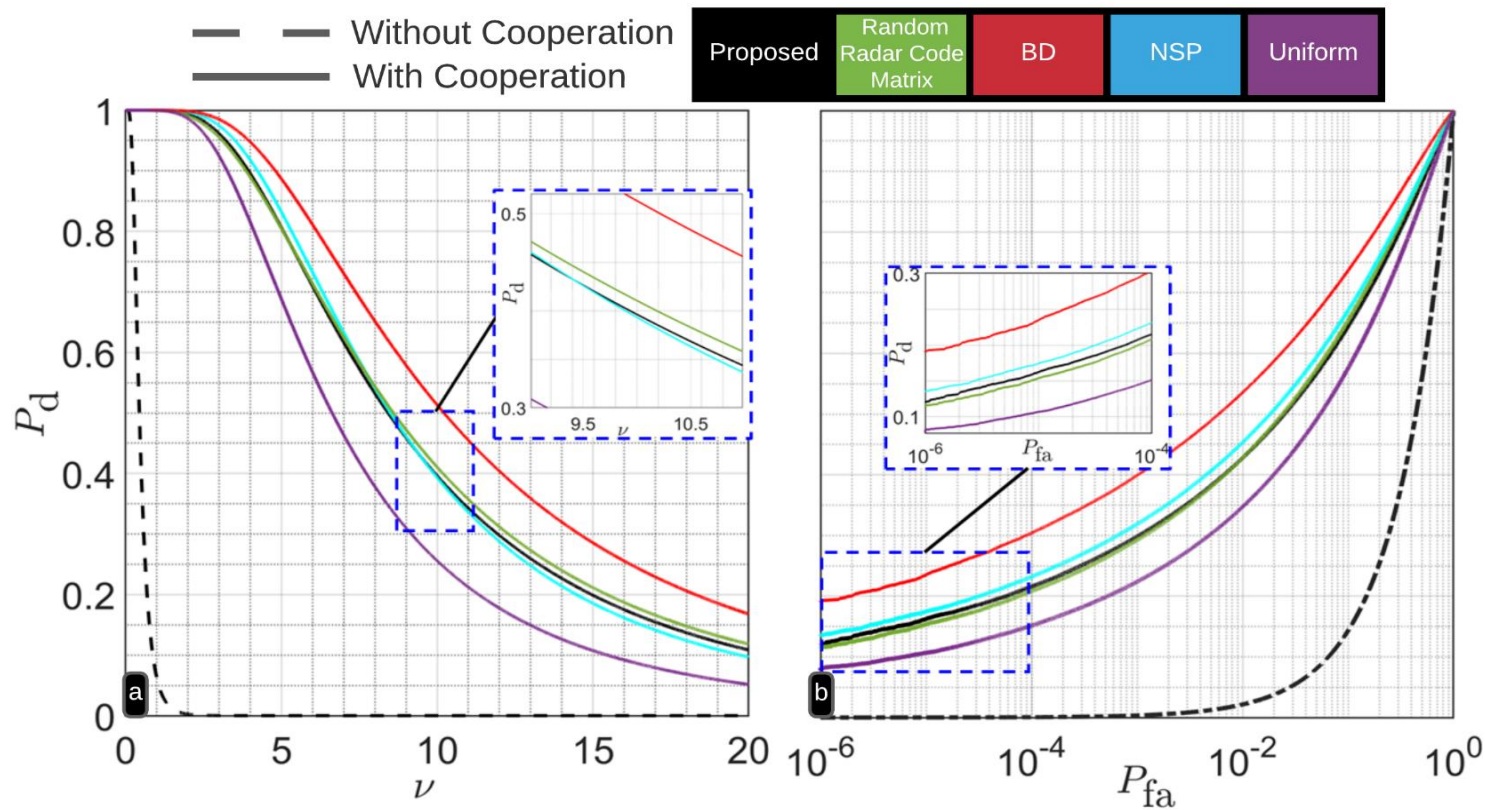
UL signal

Clutter signal

Complex Gaussian Noise vectors



Numerical Experiments



Courtesy: The Expanse (Season 5)

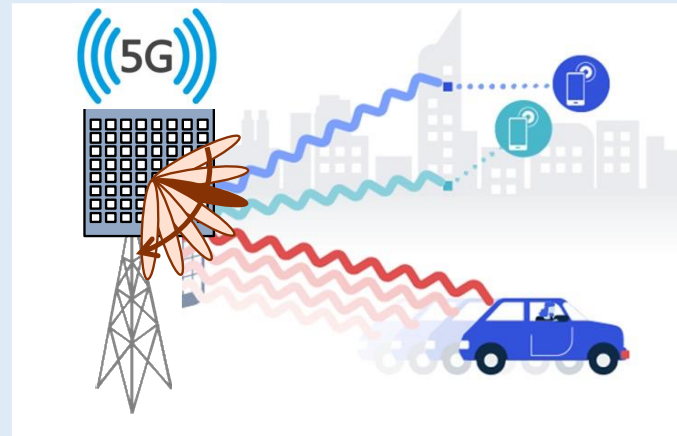


The tight-beam backscatter
we picked up



was probably a communication
with Marco.

Spectral Co-Design Learning for JRC Hybrid Beamforming



When ML makes sense in ISAC?

Model/Algorithm Deficit

- Conventional engineering approach is not applicable because models stemming from physics/mathematics/algorithms cannot be rigorously specified
- Sufficiently large training data sets exhibiting all the variation in the observed data sets available or can be created (e.g., using GANs)
- Labeling of training data can be done with a reasonable effort

Tasks

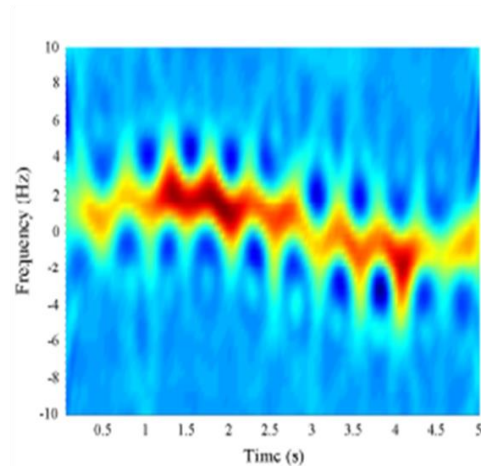
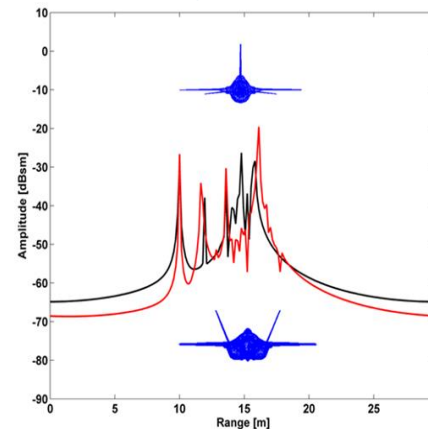
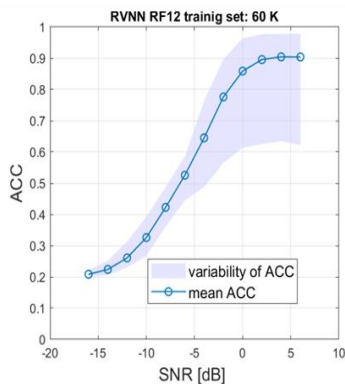
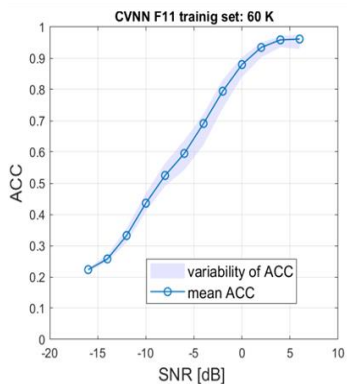
- Need for Narrow AI with super-human performance, no need for broader intelligence
- The task does not need explicit reasoning based on broader background knowledge.
- No requirement of rigorous quantitative performance guarantees/explicit explanations for how the result was found

Results

- Numerical simulations suffice instead of analytical optimality results
- Learned phenomenon remains stationary to acquire large amount of training data

Deep learning examples in radar sensing

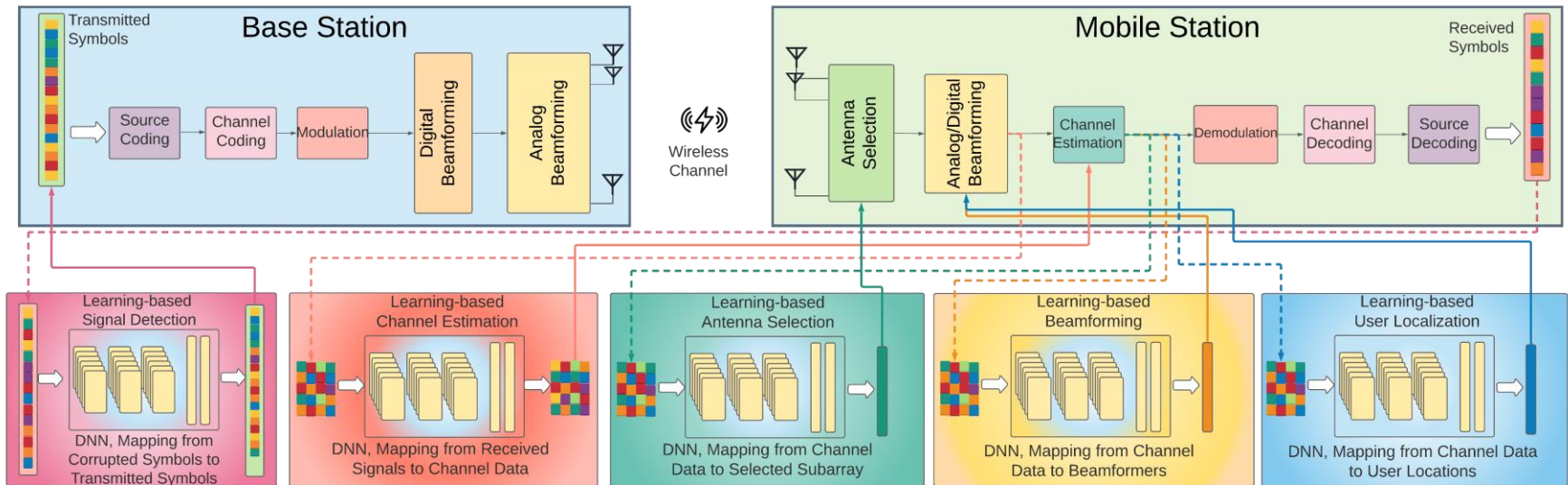
- ◆ Target classification using deep learning and HRRPs
- ◆ Waveform classification using complex-valued and real-valued NNs
- ◆ CNNs give better and more predictable performance with less training data and smaller NN



- ◆ Analysis of micro-doppler signatures

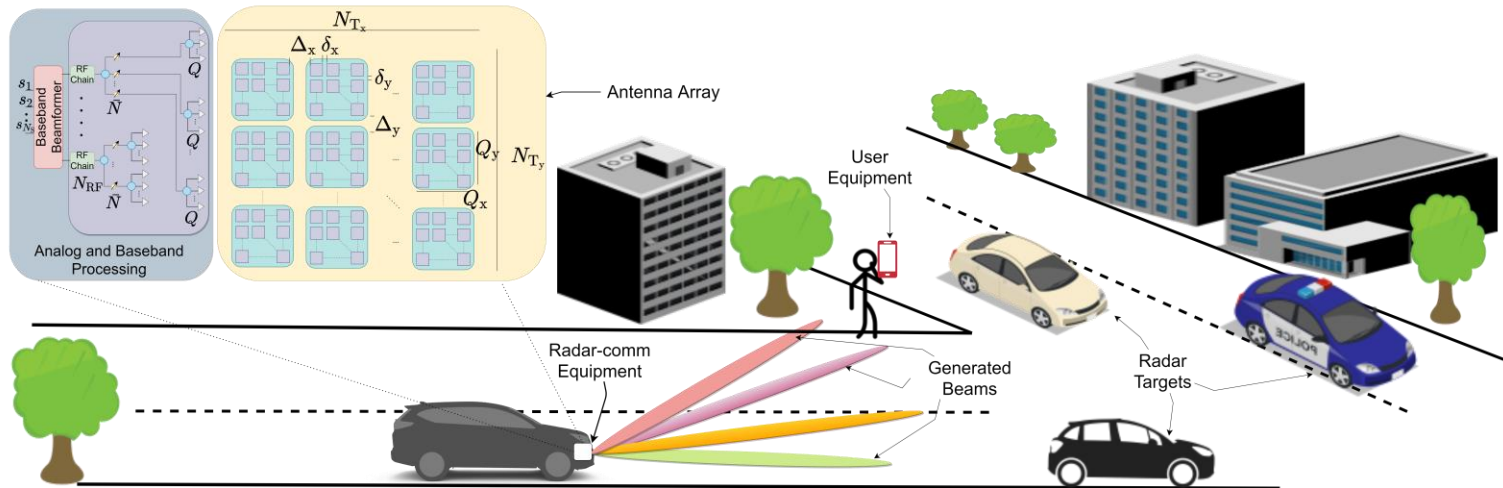
Deep Learning Applications in Comms Physical Layer

DL can be used for various PHY applications.



Elbir, Ahmet M. and Kumar Vijay Mishra. "Cognitive Learning-Aided Multi-Antenna Communications.", IEEE Wireless Communications, in press.

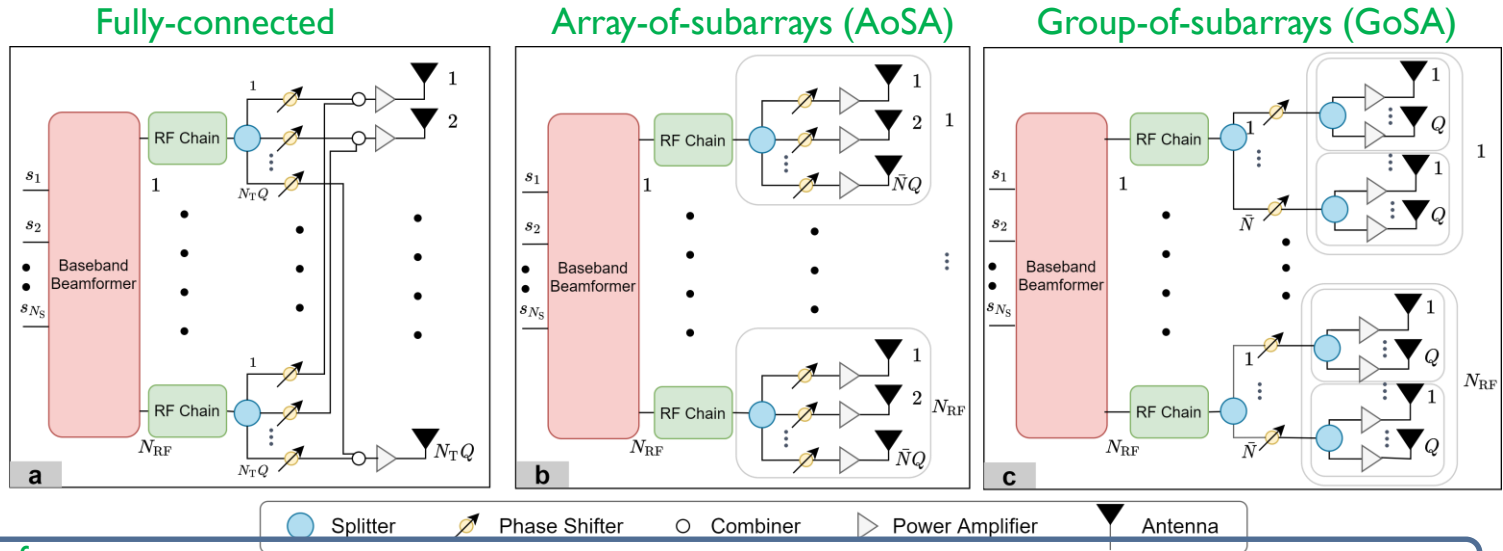
THz ISAC Hybrid Beamforming via Deep Learning



Major Challenges in THz Hybrid Beamforming :

- High path loss: LoS-dominant with multiple NLoS channel
- Ultra-massive number of antennas: Group-of-subarrays (GoSA)
- Complexity: Deep-learning-based solutions

THz ISAC Hybrid Beamforming via Deep Learning



Number of phase shifters:

$$N_T Q N_{RF}$$

$$\bar{N} Q \quad (\bar{N} = \frac{N_T}{N_{RF}})$$

$$N_T$$

Major Challenges in THz Hybrid Beamforming :

- High path loss: LoS-dominant with multiple NLoS channel
- Ultra-massive number of antennas: Group-of-subarrays (GoSA)
- Complexity: Deep-learning-based solutions

THz ISAC Hybrid Beamforming via Deep Learning

Communications

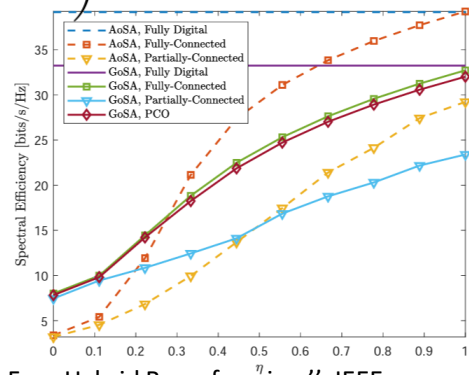
$$\begin{aligned} & \min_{\mathbf{F}_{\text{RF}}, \{\mathbf{F}_{\text{BB}}[m]\}_{m \in \mathcal{M}}} \frac{1}{M} \sum_{m \in \mathcal{M}} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m] - \mathbf{F}_{\text{C}}[m]\|_{\mathcal{F}} \\ & \text{s.t.} \quad \sum_{m \in \mathcal{M}} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m]\|_{\mathcal{F}} = MN_{\text{S}}, \\ & \quad \quad \quad |[\mathbf{F}_{\text{RF}}]_{i,j}| = \frac{1}{\sqrt{N_{\text{T}}}}, \quad \forall i, j. \end{aligned}$$

Radar

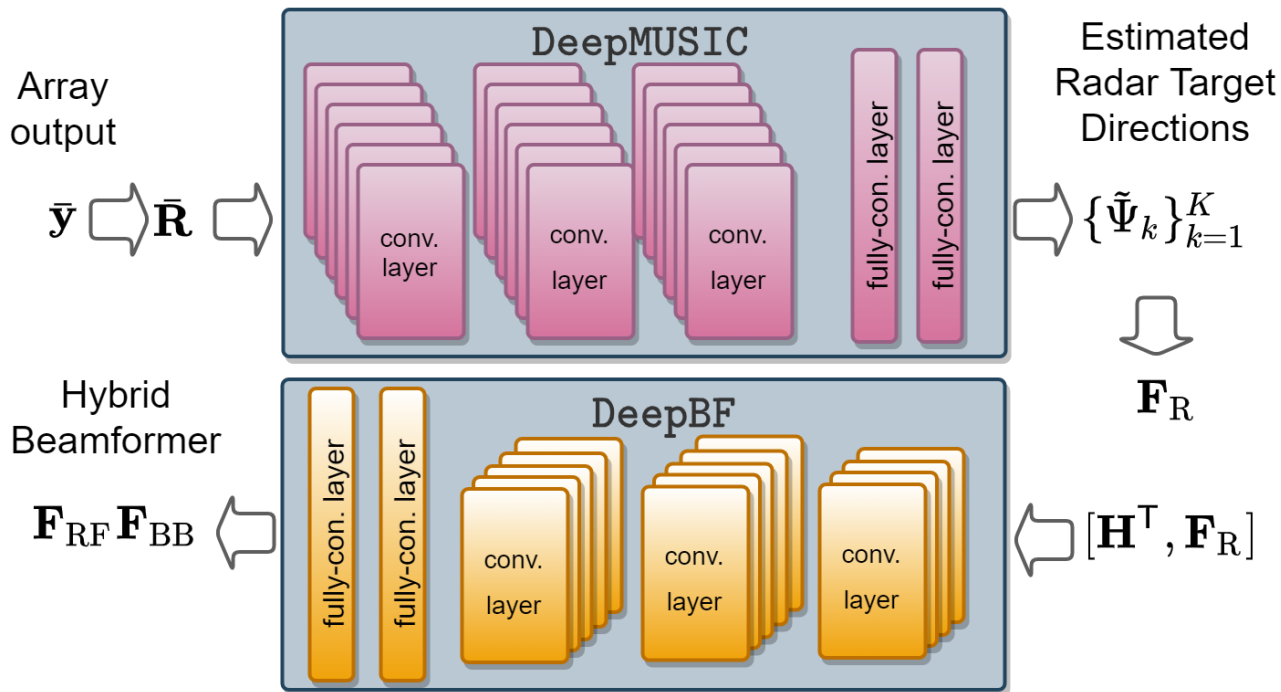
$$\begin{aligned} & \min_{\mathbf{F}_{\text{RF}}, \{\mathbf{F}_{\text{BB}}[m], \mathbf{P}[m]\}_{m \in \mathcal{M}}} \frac{1}{M} \sum_{m \in \mathcal{M}} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m] - \mathbf{F}_{\text{R}} \mathbf{P}[m]\|_{\mathcal{F}} \\ & \text{s.t.} \quad \sum_{m \in \mathcal{M}} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m]\|_{\mathcal{F}} = MN_{\text{S}}, \\ & \quad \quad \quad |[\mathbf{F}_{\text{RF}}]_{i,j}| = \frac{1}{\sqrt{N_{\text{T}}}}, \quad \forall i, j, \\ & \quad \quad \quad \mathbf{P}[m] \mathbf{P}^{\text{H}}[m] = \mathbf{I}_{N_{\text{S}}} \end{aligned}$$

JRC Hybrid Beamforming Design

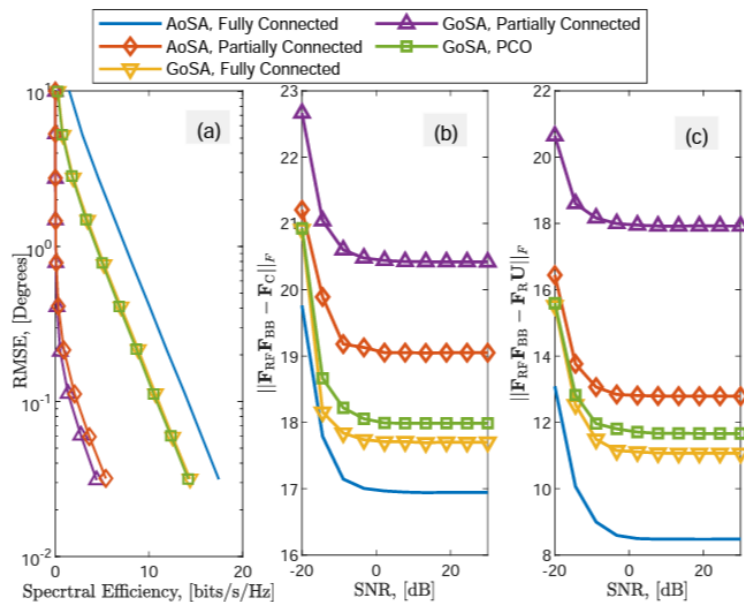
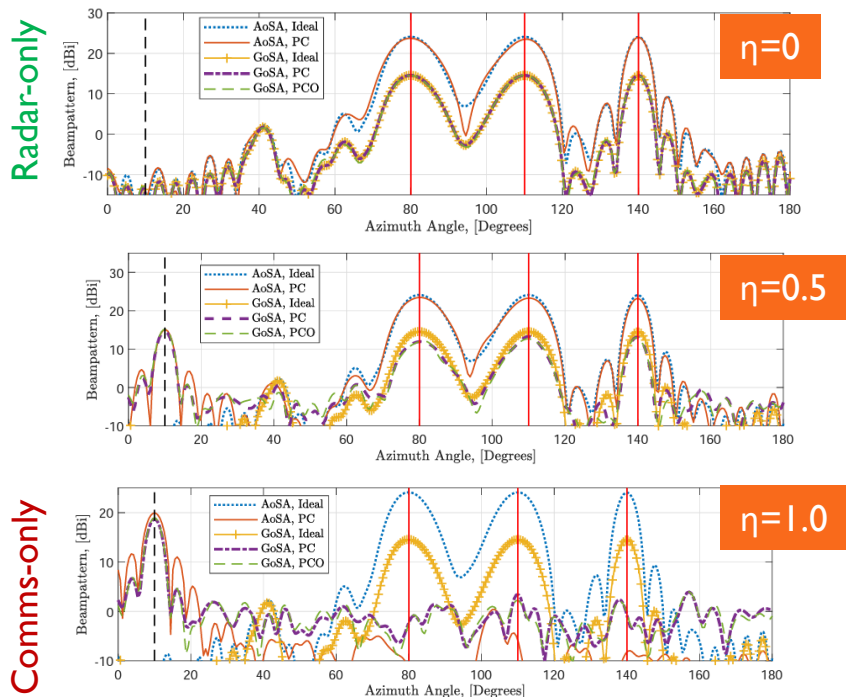
$$\begin{aligned} & \min_{\mathbf{F}_{\text{RF}}, \{\mathbf{F}_{\text{BB}}[m], \mathbf{P}[m]\}_{m \in \mathcal{M}}} \frac{1}{M} \sum_{m \in \mathcal{M}} \left(\eta \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m] - \mathbf{F}_{\text{C}}[m]\|_{\mathcal{F}} + \bar{\eta} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m] - \mathbf{F}_{\text{R}} \mathbf{P}[m]\|_{\mathcal{F}} \right) \\ & \text{s.t.} \quad \sum_{m \in \mathcal{M}} \|\mathbf{F}_{\text{RF}} \mathbf{F}_{\text{BB}}[m]\|_{\mathcal{F}} = MN_{\text{S}}, \\ & \quad \quad \quad |[\mathbf{F}_{\text{RF}}]_{i,j}| = \frac{1}{\sqrt{N_{\text{T}}}}, \quad \forall i, j \in \mathcal{S}, |[\mathbf{F}_{\text{RF}}]_{i,j}| = 0, \quad \forall i, j \in \bar{\mathcal{S}}, \\ & \quad \quad \quad \mathbf{P}[m] \mathbf{P}^{\text{H}}[m] = \mathbf{I}_{N_{\text{S}}} \end{aligned}$$



THz ISAC Hybrid Beamforming via Deep Learning



THz ISAC Hybrid Beamforming via Deep Learning

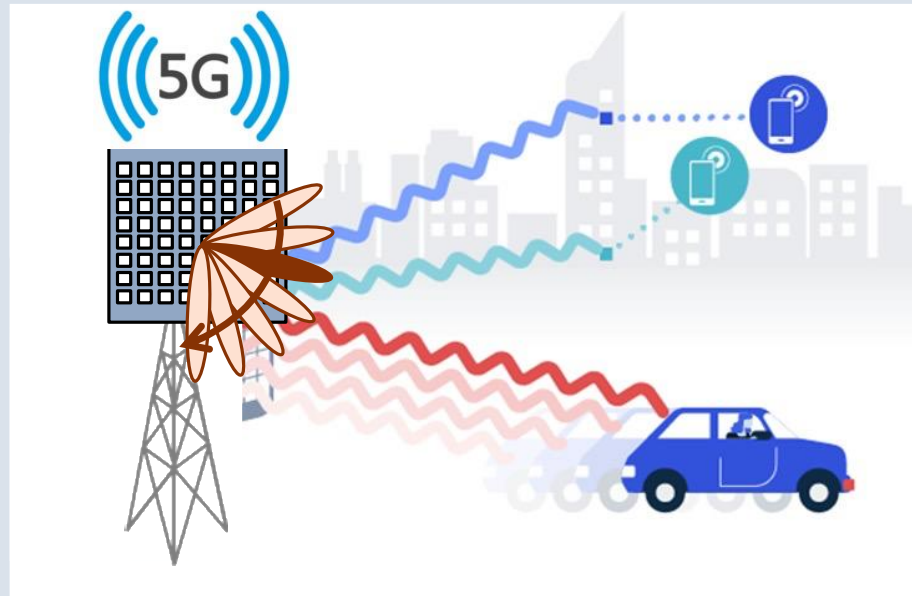




The decoy ships will jump into the enemy star system at extreme radar range from the Cylon asteroid

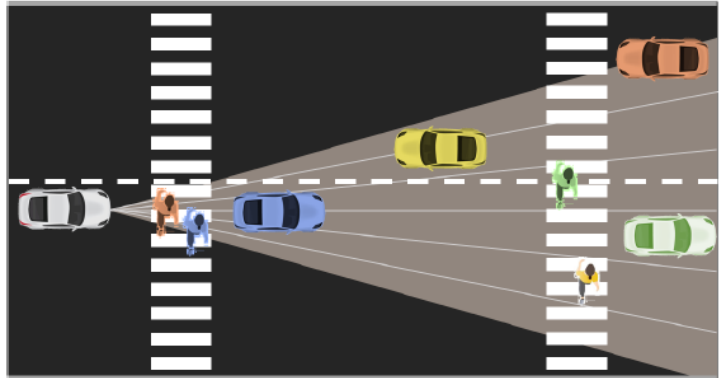
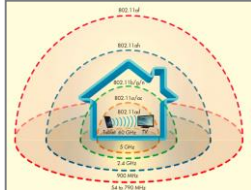
Opportunistic ISAC

Using Wi-Fi Protocol for Radar



802-11ad-Based Joint Radar-Comms

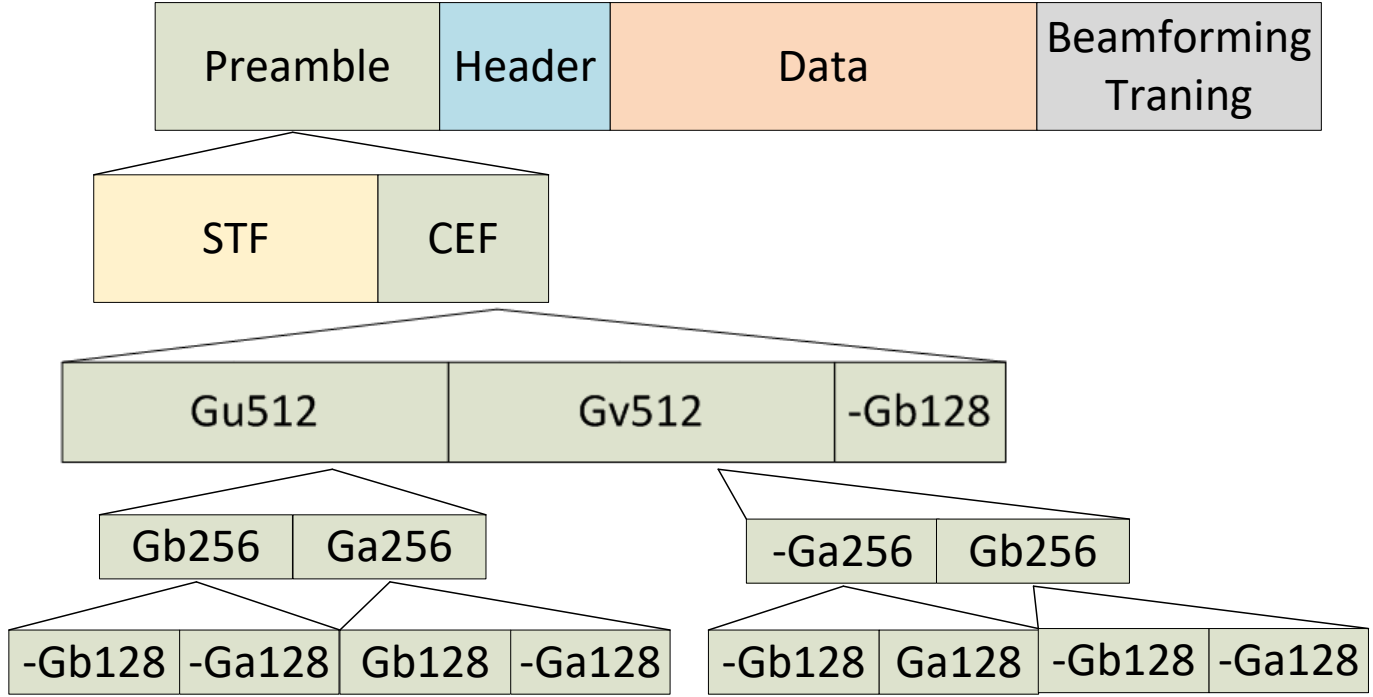
- IEEE 802.11ad Wi-Fi standard enables high-throughput (7 Gbps) at 60 GHz
 - Very high rate (~GHz) ADCs → More power, space and cost
 - Can be exploited for a concurrent radar application
- Applications: parking assistance, lane change assistance, object detection



Parameters	Current literature	Proposed radar
Range	Long range (200m)	Short range (40m)
Target model	Simple point targets	Extended targets
Type of target	Static targets	Dynamic targets
Golay sequence	Standard	Modified / Doppler resilient

IEEE 802.11ad Frame Structure

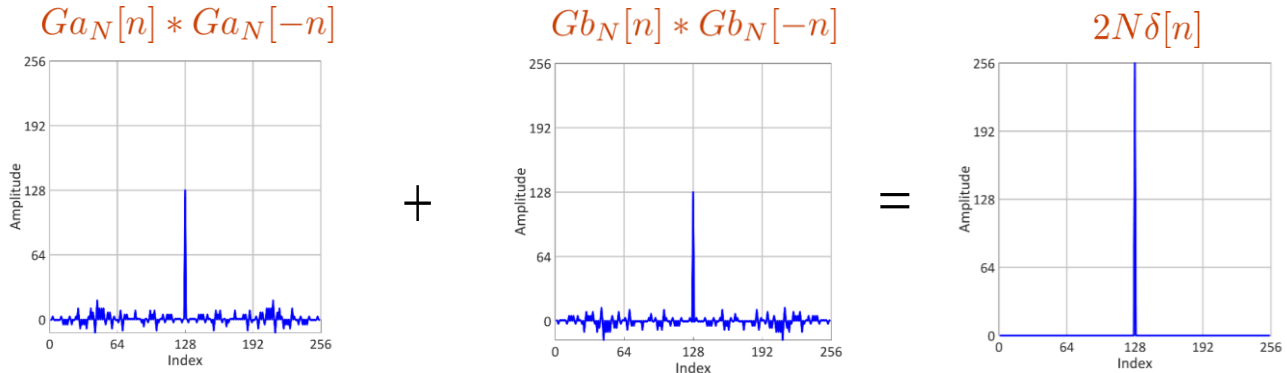
- ◆ Single Carrier Physical layer (SCPHY) encapsulates Golay sequences



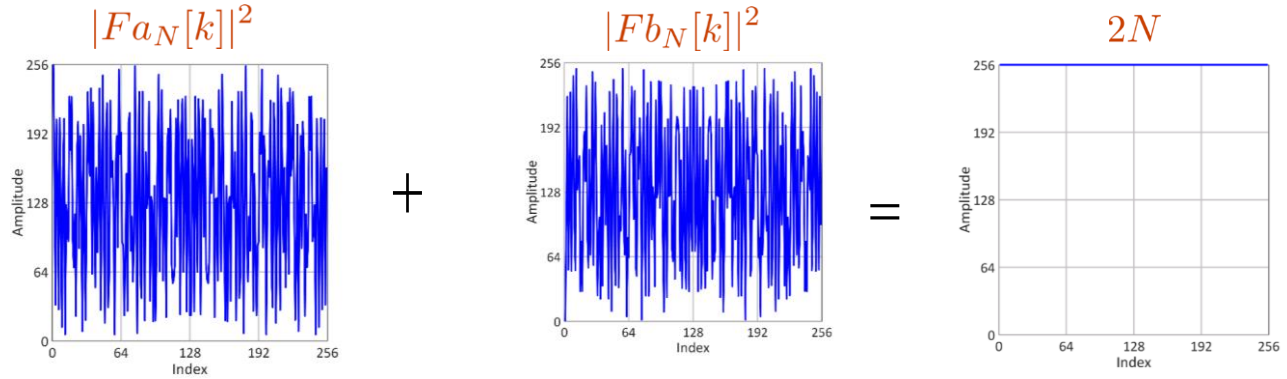
- ◆ 802.11ad Golay sequences: Two 256-length or four 128-length pairs

Golay Complementary Sequences (Golay Pairs)

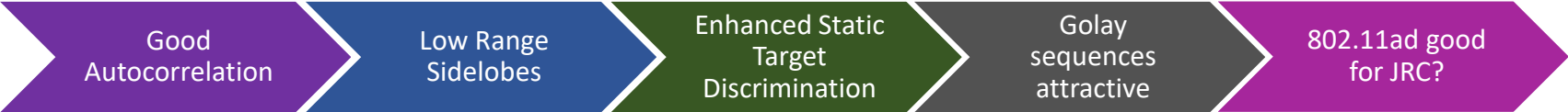
◆ Time-domain Property: Zero sidelobes



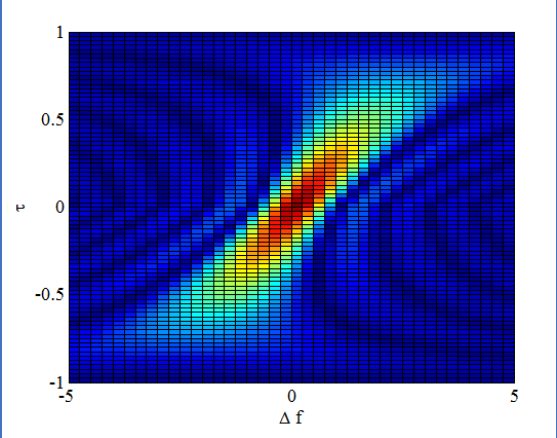
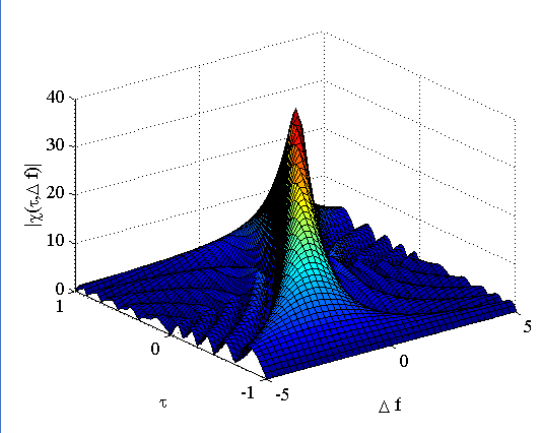
◆ Frequency-domain Property: Constant spectrum



Good Autocorrelation, but Doppler Resilience?



Ambiguity Function : $AF(t, \omega) = \int x(\tau)x^*(\tau - t)e^{j\omega\tau}d\tau$



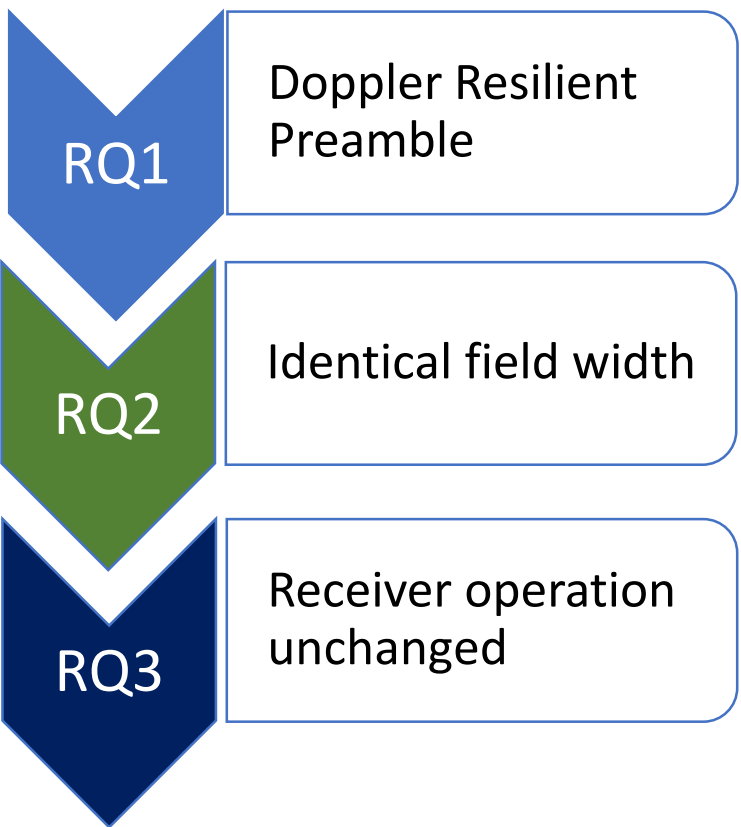
Doppler-Resilient FMCW Waveform

Is 802.11ad Preamble Doppler-Resilient ?

$$G_{a,N}[n] * G_{a,N}[-n] + G_{b,N}[n] * G_{b,N}[-n] = 2N\delta[n].$$

$$(G_{a,N}[n] * G_{a,N}[-n]) + (G_{b,N}[n] * G_{b,N}[-n]) e^{-j\theta} \neq 2N\delta[n]$$

Modification to 802.11ad



Prouhet-Thue-Morse (PTM) (Pezeshki et al., 2008) sequence to make the protocol Doppler-resilient

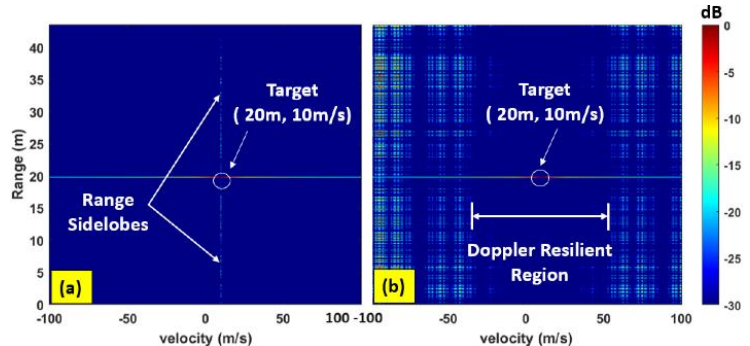
Prouhet-Thue-Morse (PTM) Sequence	Modified Golay sequence
$q_p = \begin{cases} 0, & \text{if } p = 0 \\ q_{\frac{p}{2}}, & \text{if } (p \text{ modulo } 2) = 0 \\ \overline{q_{\frac{p-1}{2}}}, & \text{if } (p \text{ modulo } 2) = 1, \end{cases}$	$\begin{cases} \text{if } q_p = 0, \{G_{a,N}[n], G_{b,N}[n]\} \\ \text{if } q_p = 1, \{-G_{b,N}[-n], G_{a,N}[-n]\} \end{cases}$

Example

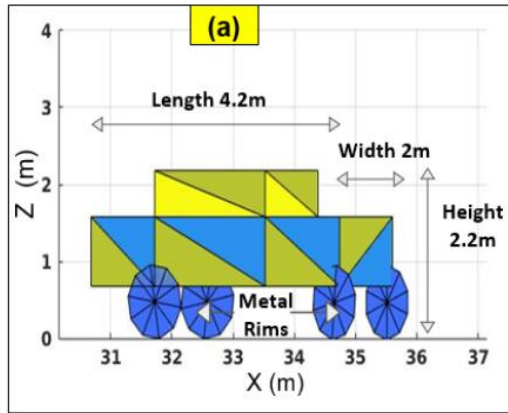
PTM Sequence: $[01] : G_{a,N}[n], G_{b,N}[n], -G_{b,N}[-n], G_{a,N}[-n]$:

$$\sum_{p=0}^3 e^{-jp\theta} (G_{p,N}[n] * G_{p,N}[-n]) \approx 1((G_{1,N}[n] * G_{1,N}[-n]) + (G_{3,N}[n] * G_{3,N}[-n]))$$

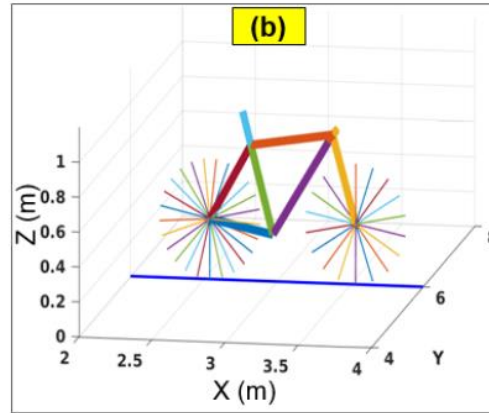
$$+ 2((G_{2,N}[n] * G_{2,N}[-n]) + (G_{3,N}[n] * G_{3,N}[-n]))$$

$$= (2N + 2(2N))\delta[n] = 6N\delta[n].$$


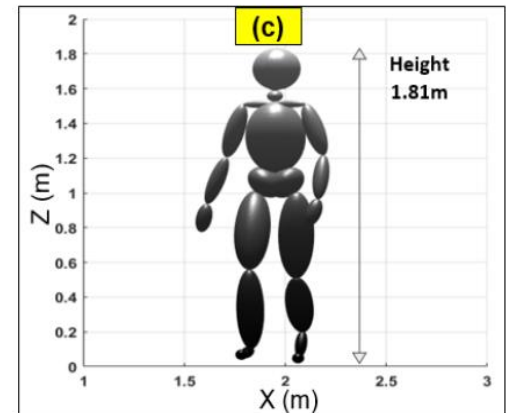
Extended Target Modeling (via PyBullet)



CAR

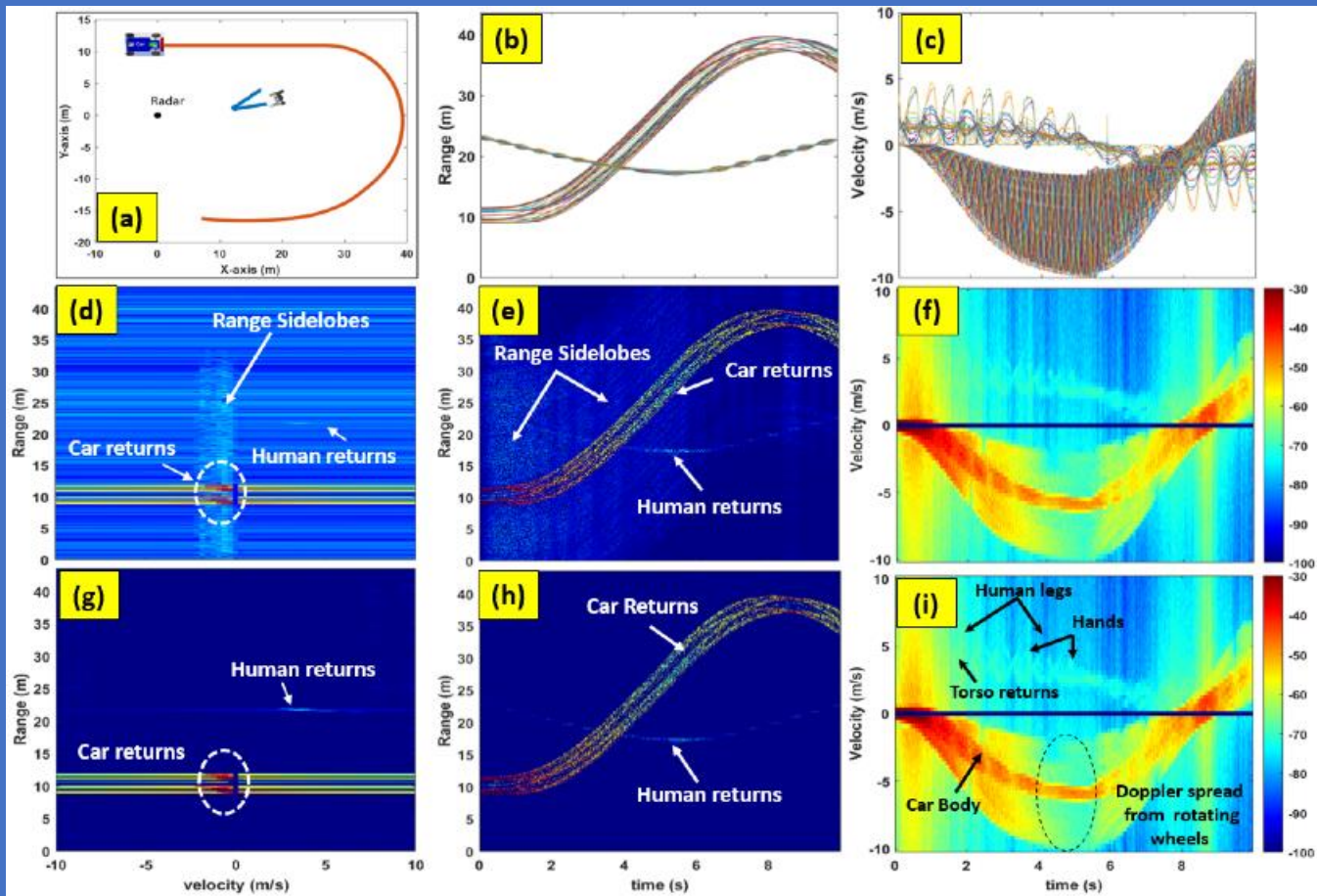


BICYCLE

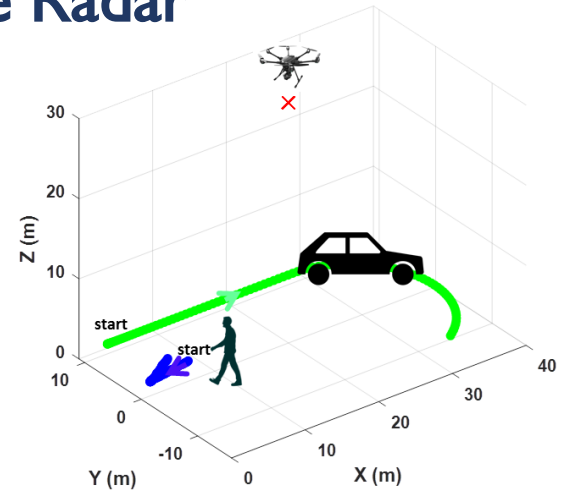
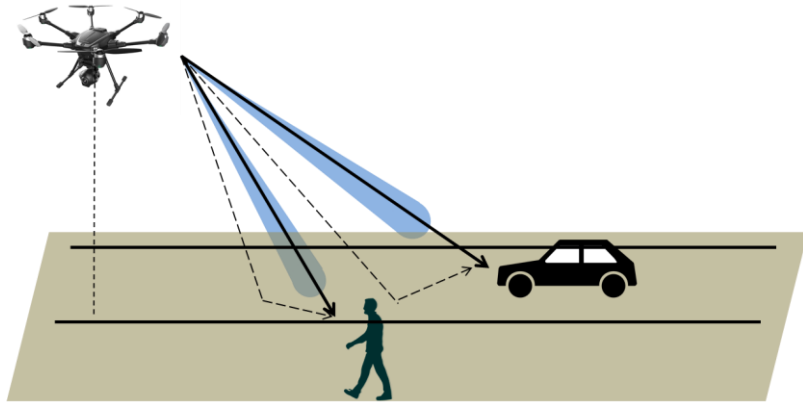


PEDESTRIAN

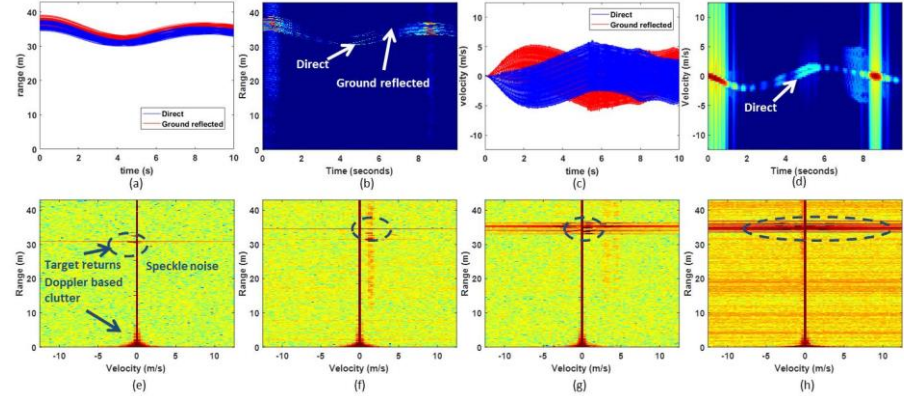
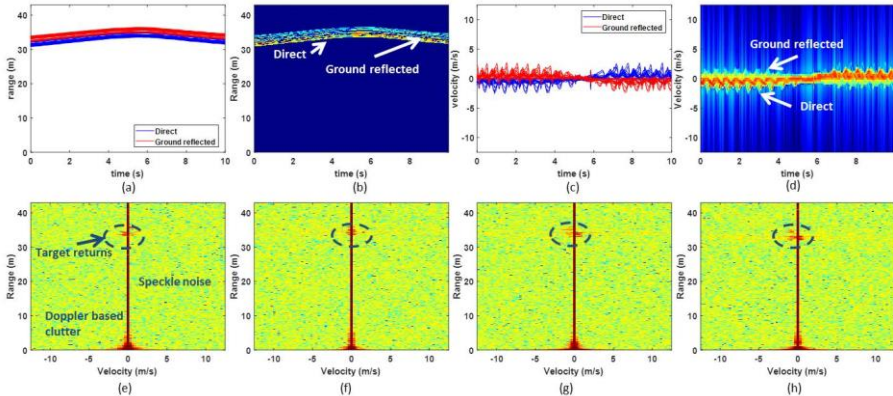
Extended Target Modeling Results – Multiple Targets



802.11ad-Based UAV-Borne Radar



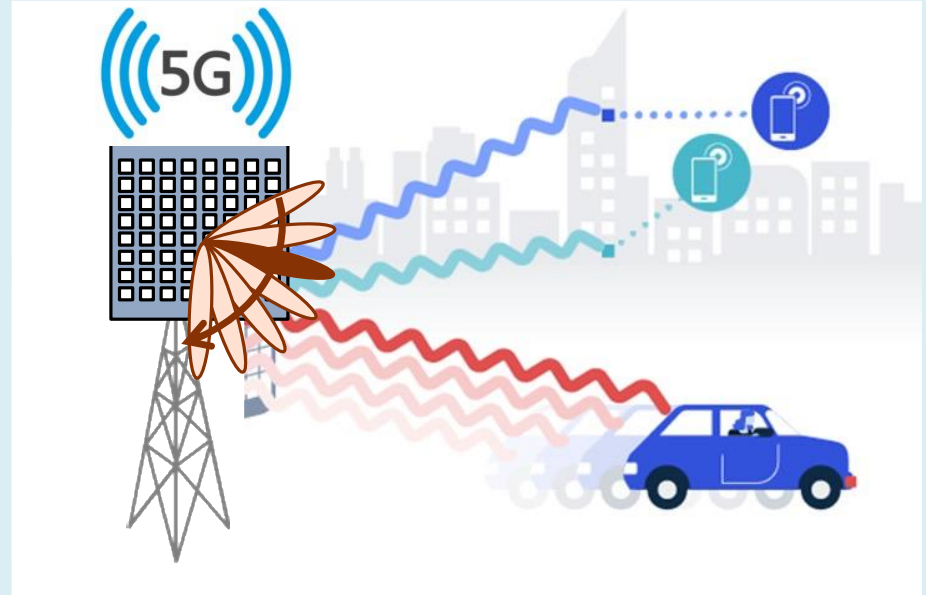
Surface clutter models and PyBullet modeling used to obtain the signatures



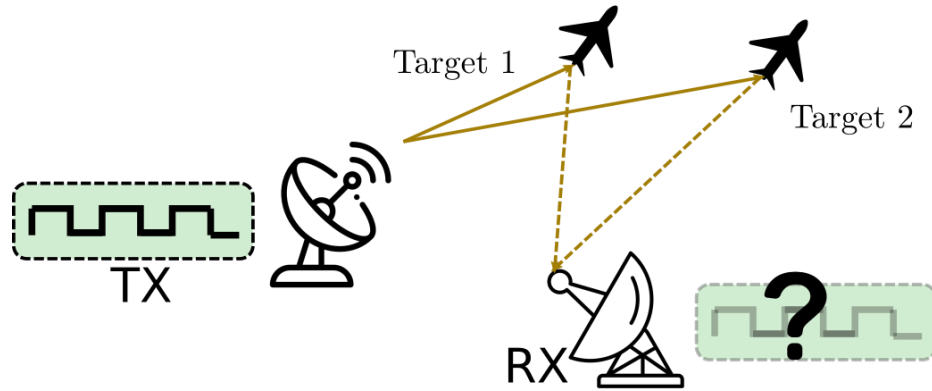
Courtesy: Species II

We had a malfunction
in the K.U. band antenna.

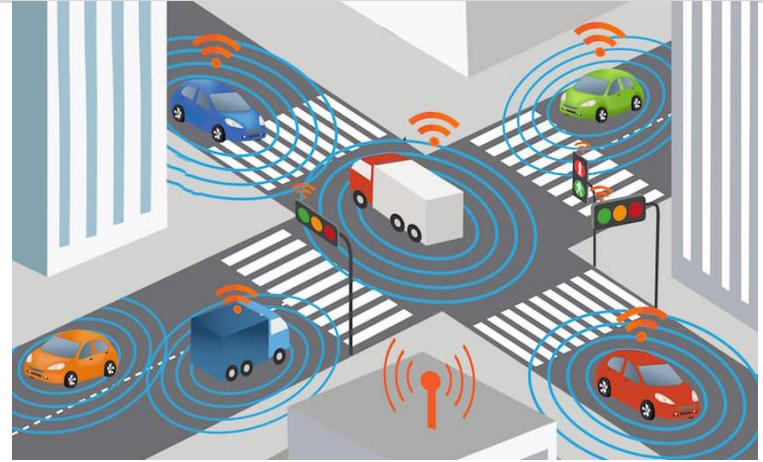
Spectral Co-Existence Dual-Blind Deconvolution



Co-Existence Receiver



Passive Radar



Dynamic Communications

Problem: Neither the transmitted signals nor the channels are known

Dual-Blind Deconvolution Problem

$$y(t) = x_r(t) * h_r(t) + x_c(t) * h_c(t)$$

Transmitted radar signal

$$\sum_{p=0}^{P-1} s(t - pT)$$

Radar Channel

$$\sum_{\ell=0}^{L-1} [\alpha_r]_{\ell} \delta(t - [\tilde{\tau}_r]_{\ell}) e^{-j2\pi[\tilde{\nu}_r]_{\ell} t}$$

PRI T

Radar waveform \mathbf{s}

Propagation paths Q Symbols \mathbf{g}

Radar targets L Time delay τ

Subcarriers K Attenuation α

Transmitted pulses P Doppler ν

Transmitted communications signal

$$\sum_{p=0}^{P-1} \sum_{k=0}^{K-1} [g_p]_k e^{-j2\pi k \Delta f (t - pT)}$$

Communications channels

$$\sum_{q=0}^{Q-1} [\alpha_c]_q \delta(t - [\tilde{\tau}_c]_q) e^{-j2\pi[\tilde{\nu}_c]_q t}$$

$$[\mathbf{y}]_v = \sum_{\ell=0}^{L-1} [\alpha_r]_{\ell} [\mathbf{s}]_n e^{-j2\pi(n[\tau_r]_{\ell} + p[\nu_r]_{\ell})} + \sum_{q=0}^{Q-1} [\alpha_c]_q [\mathbf{g}_p]_n e^{-j2\pi(n[\tau_c]_q + p[\nu_c]_q)}$$

Unknown variables: set of channel parameters $\{\tau_r, \nu_r, \alpha_r, \tau_c, \nu_c, \alpha_c\}$ and the transmit signals \mathbf{s}, \mathbf{g}

Atomic norm minimization framework

- Leveraging the **sparse nature** of the channels, we use ANM framework for **super-resolved** estimations of **continuous-valued** channel parameters.

- We define the atomic sets as

$$\mathcal{A}_r = \{\mathbf{u}\mathbf{a}(\mathbf{r})^H : \mathbf{r} \in [0,1]^2, \|\mathbf{u}\|_2 = 1\}$$

$$\mathcal{A}_c = \{\mathbf{v}\mathbf{a}(\mathbf{c})^H : \mathbf{c} \in [0,1]^2, \|\mathbf{v}\|_2 = 1\}$$

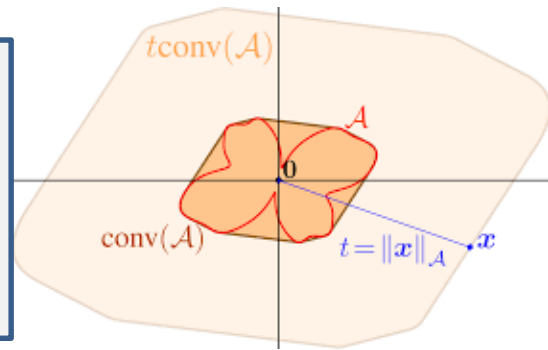
- The corresponding atomic norm are given by

$$\|\mathbf{Z}_r\|_{\mathcal{A}_r} = \inf_{[\alpha_r]_\ell, \mathbf{r}_\ell \in [0,1]^2, \|\mathbf{u}\|_2=1} \{\sum_\ell |[\alpha_r]_\ell| \mid \mathbf{Z}_r = \sum_\ell [\alpha_r]_\ell \mathbf{a}(\mathbf{r}_\ell) \mathbf{u}^H\}$$

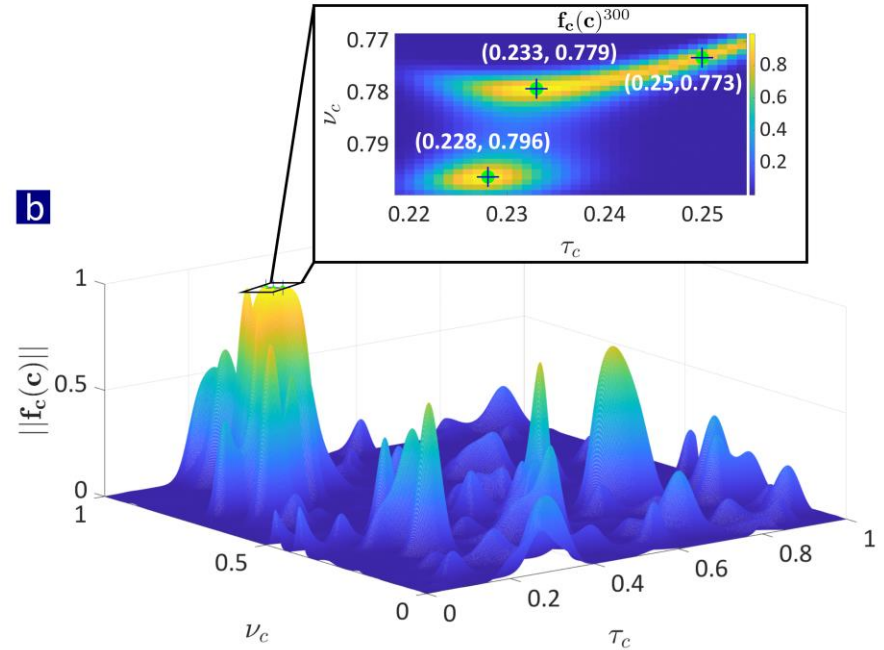
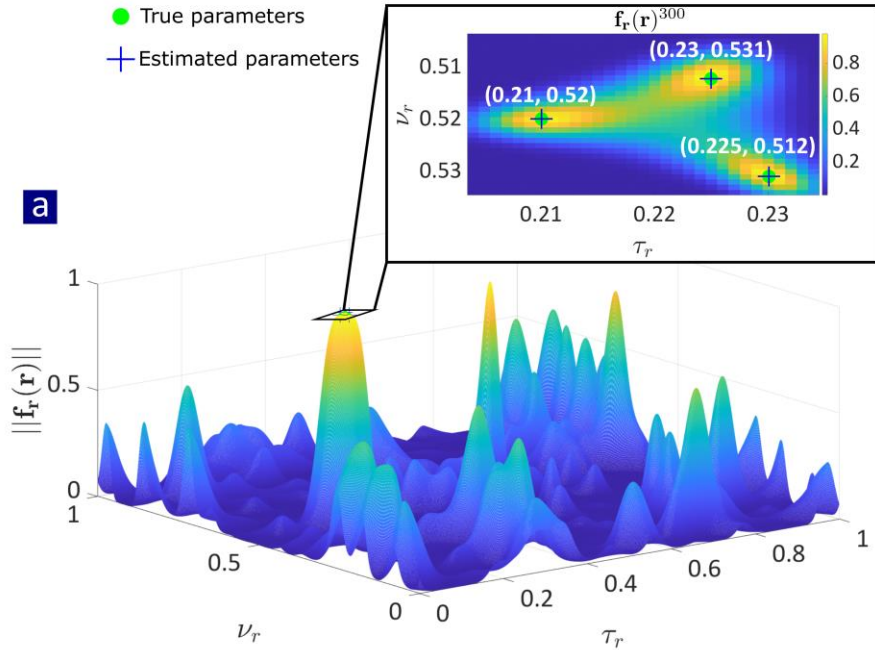
$$\|\mathbf{Z}_c\|_{\mathcal{A}_c} = \inf_{[\alpha_c]_q, \mathbf{c}_q \in [0,1]^2, \|\mathbf{v}\|_2=1} \{\sum_q |[\alpha_c]_q| \mid \mathbf{Z}_c = \sum_q [\alpha_c]_q \mathbf{a}(\mathbf{c}_q) \mathbf{v}^H\}$$

- The primal optimization problem is given by

$$\underset{\mathbf{Z}_r, \mathbf{Z}_c}{\text{minimize}} \|\mathbf{Z}_r\|_{\mathcal{A}_r} + \|\mathbf{Z}_c\|_{\mathcal{A}_c} \text{ subject to } \mathbf{y} = \mathfrak{N}_r(\mathbf{Z}_r) + \mathfrak{N}_c(\mathbf{Z}_c)$$



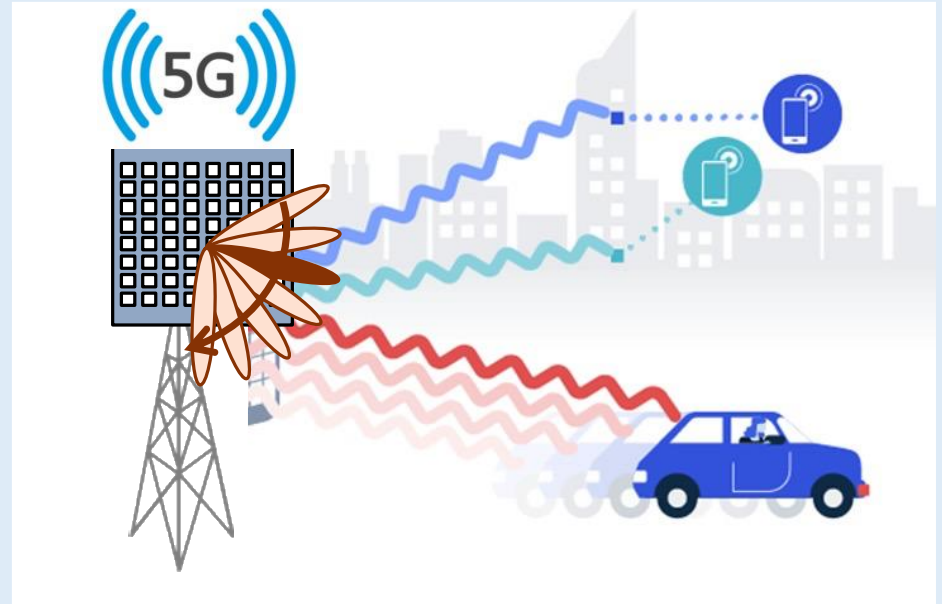
Localization for single Rx



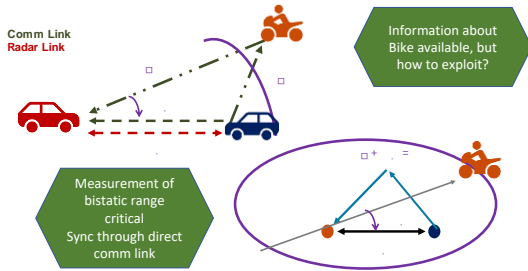
Courtesy:
Firefly (S01E09)

Well, except for the com static, I'm piping out on all frequencies. We'll show up on their screen as a radar glitch if they aren't looking close.

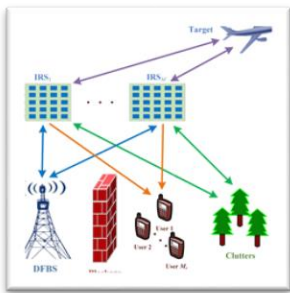
Other Distributed ISAC Architectures



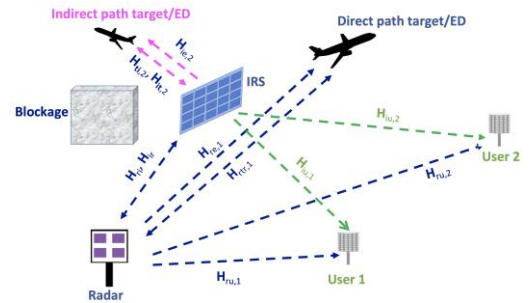
Emerging Distributed JRC/ISAC Trends



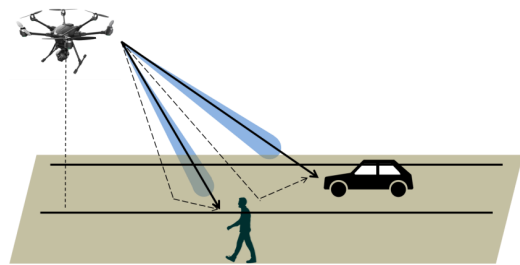
Sensor Fusion



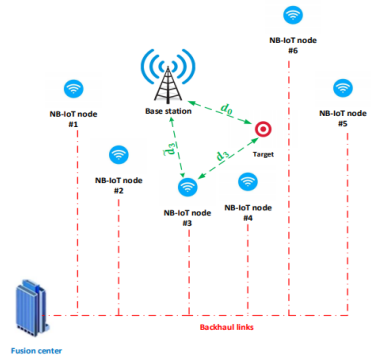
IRS-Aided JRC



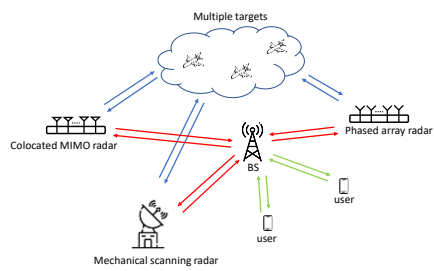
Secure IRS-Aided DFRC



Drone-Borne ISAC



Passive ISAC



Heterogeneous ISAC

S. H. Dokhanchi, M. R. B. Shankar, K. V. Mishra, and B. Ottersten, "Enhanced Automotive Target Detection through Radar and Communications Sensor Fusion," IEEE ICASSP 2021.

S. Sedighi, K. V. Mishra, M. R. B. Shankar and B. Ottersten, "Localization With One-Bit Passive Radars in Narrowband Internet-of-Things Using Multivariate Polynomial Optimization," IEEE T-SP, 2021.

A. M. Elbir, K. V. Mishra and S. Chatzinotas, "Terahertz-Band Joint Ultra-Massive MIMO Radar-Communications: Model-Based and Model-Free Hybrid Beamforming," IEEE J-STSP, 2021.

S. S. Ram and K. V. Mishra, "UAV-Based Urban Monitoring Using on-Board 802.11 ad Radar," IEEE SAM 2022.

L. Wu, K. V. Mishra, M. R. B. Shankar and B. Ottersten, "Heterogeneously-Distributed Joint Radar Communications: Bayesian Resource Allocation," IEEE J-SAC, 2022.

T. Wei, L. Wu, K. V. Mishra, M. R. B. Shankar and B. Ottersten, "Multi-IRS-Aided Wideband Integrated Sensing and Communications," 2022.

Thank you!

Signal Processing for Joint Radar- Communications

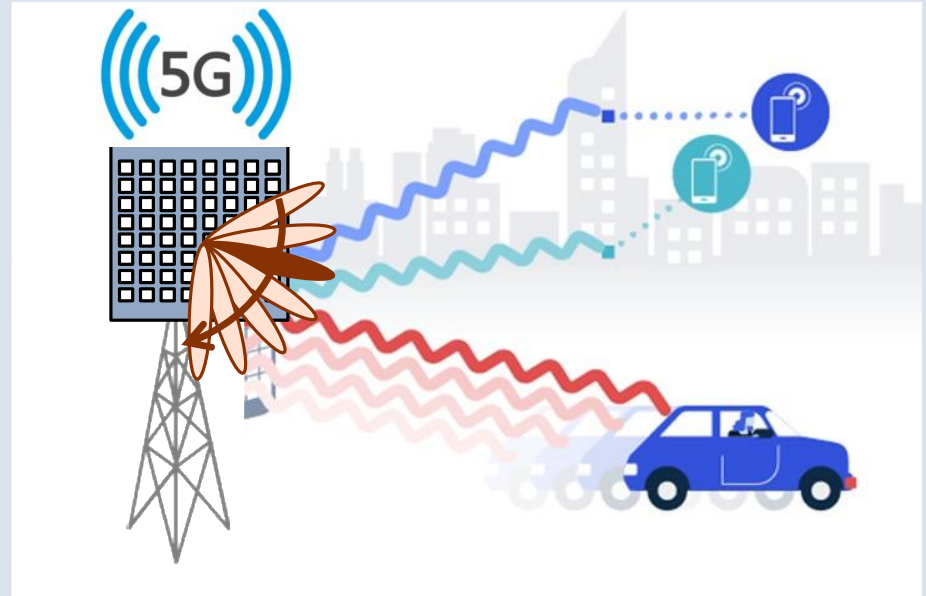
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